

FIG. 1

METHOD FOR PROVIDING SENSORY FEEDBACK TO THE
OPERATOR OF A PORTABLE MEASUREMENT MACHINE

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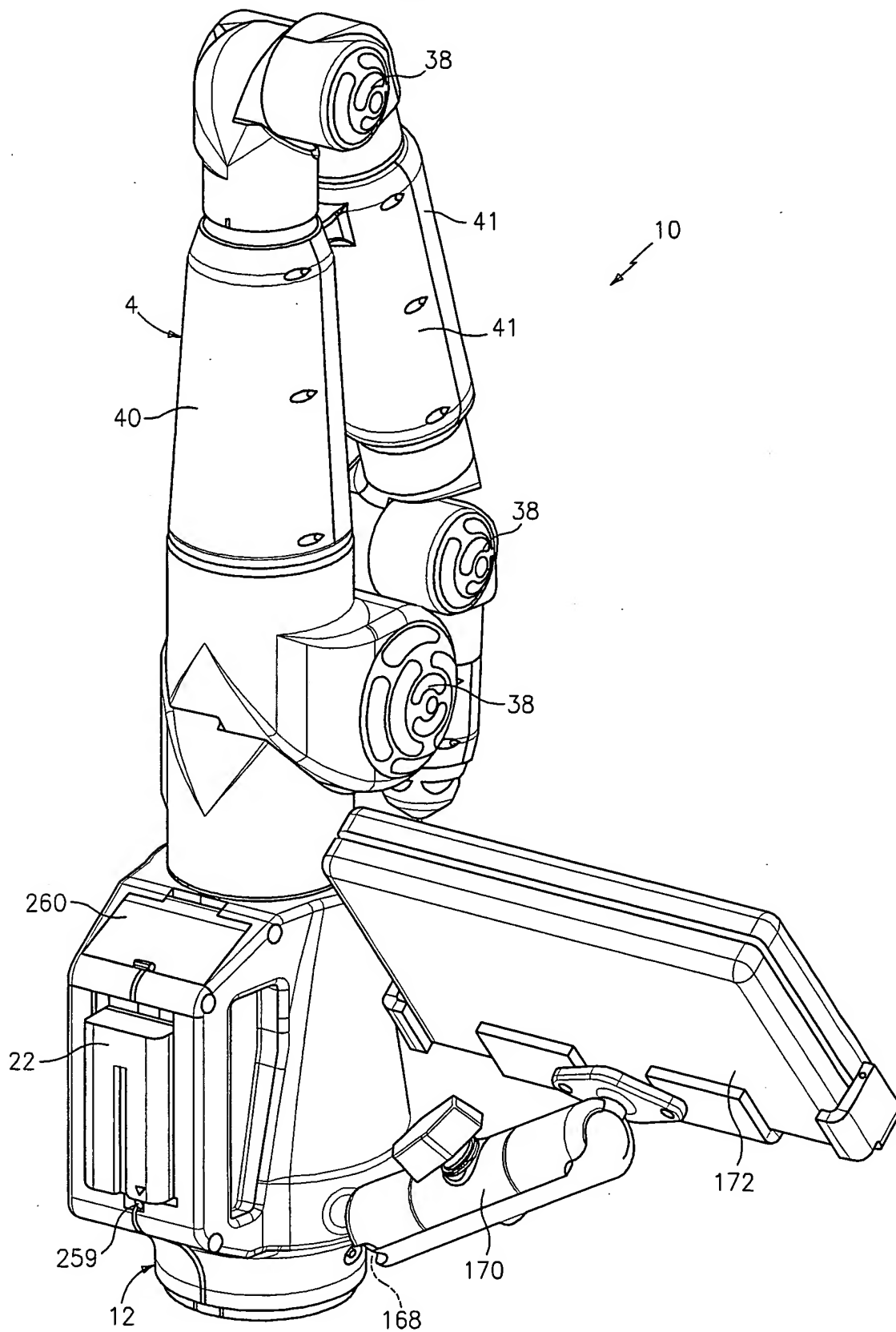


FIG. 2

METHOD FOR PROVIDING SENSORY FEEDBACK TO THE
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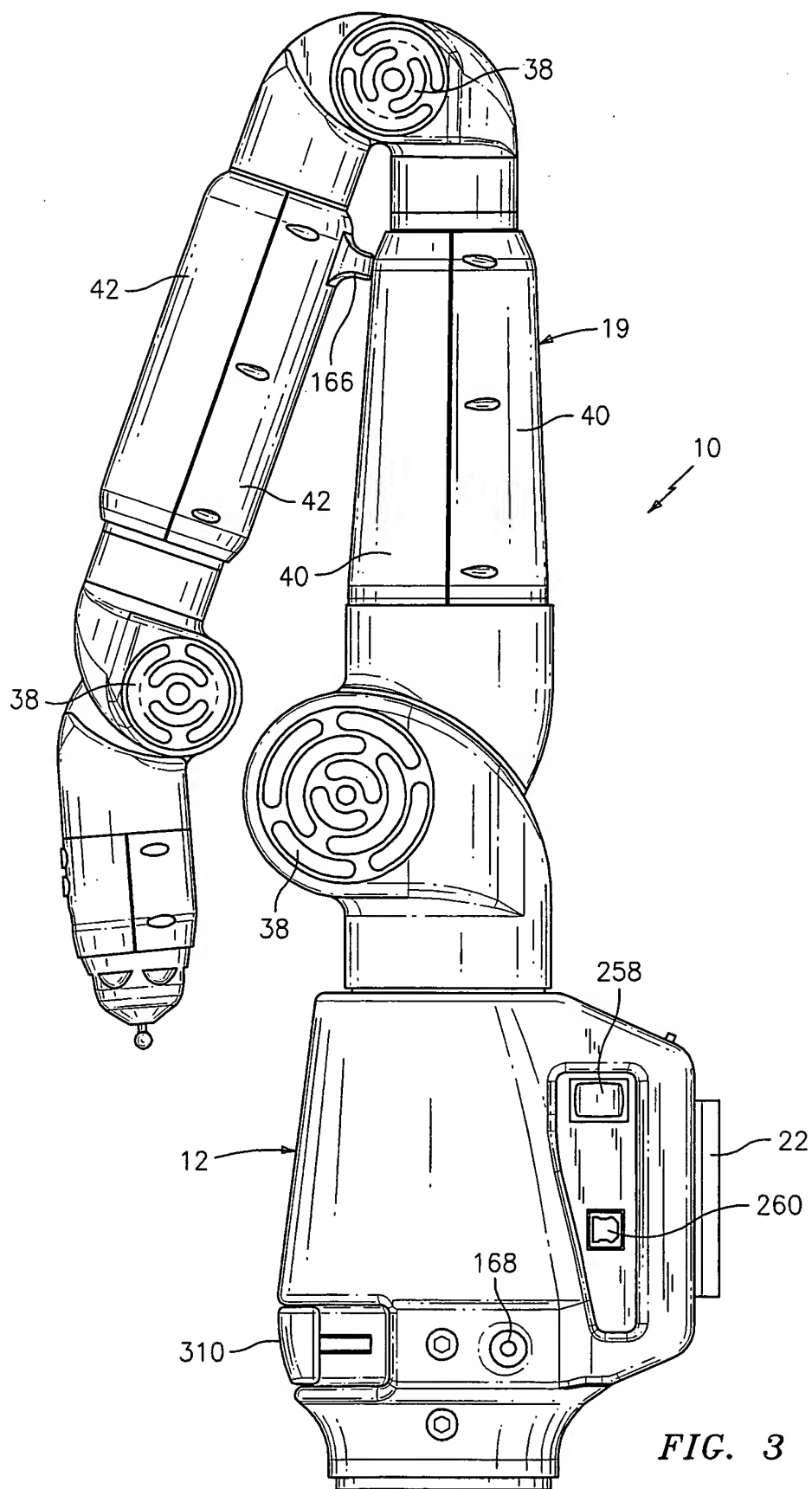


FIG. 3

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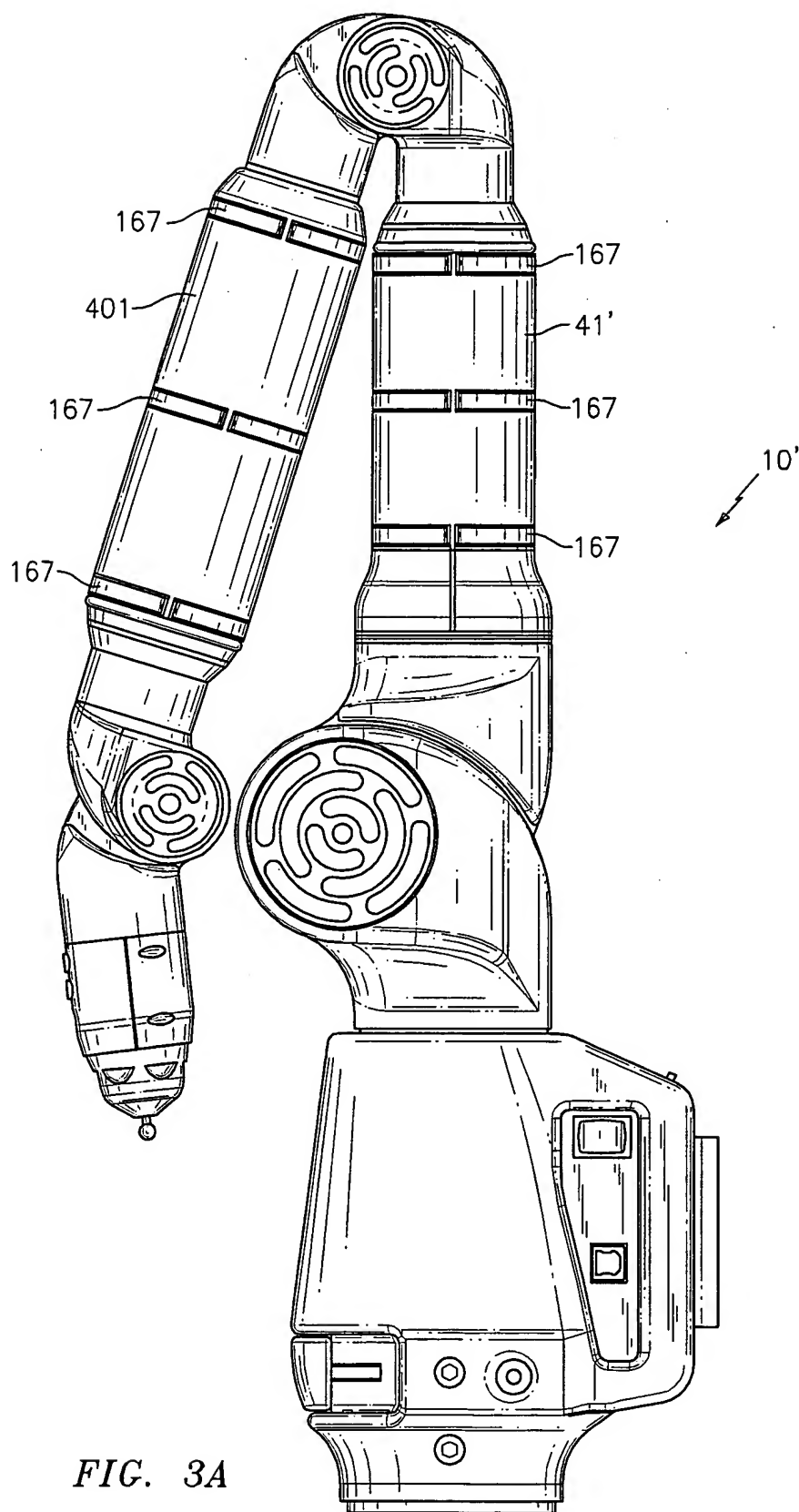


FIG. 3A

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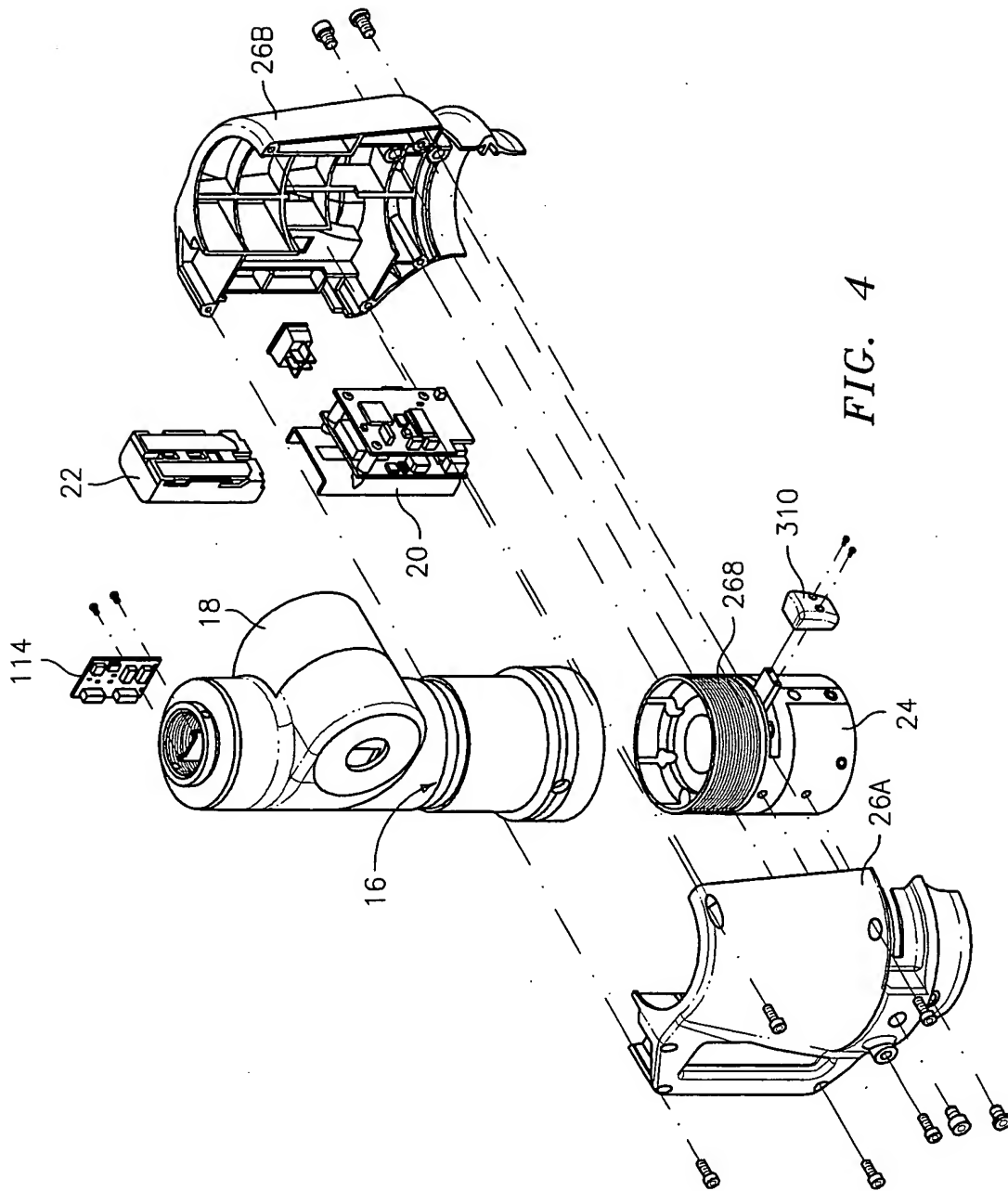


FIG. 4

FIG. 5

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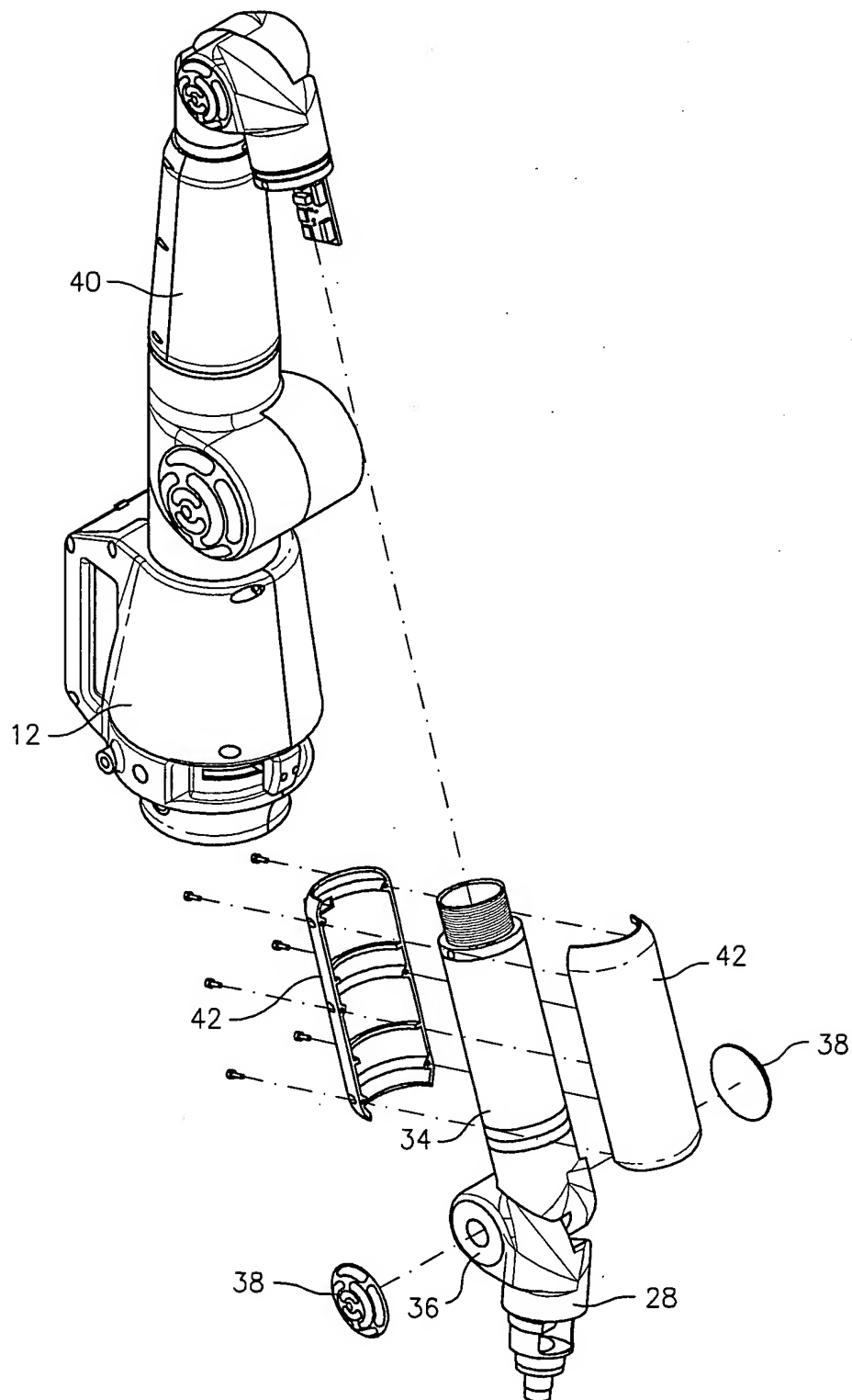


FIG. 6

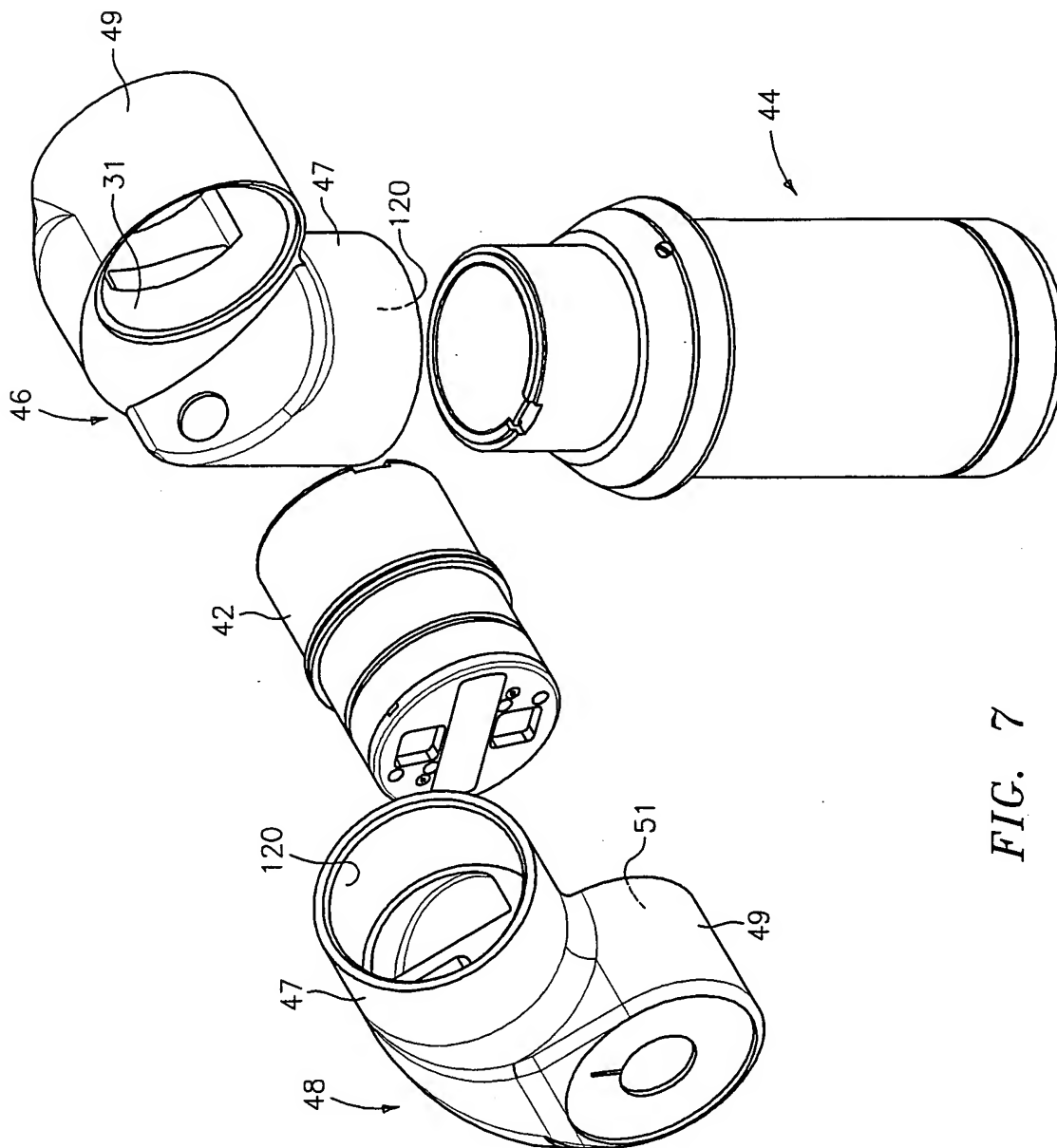


FIG. 7

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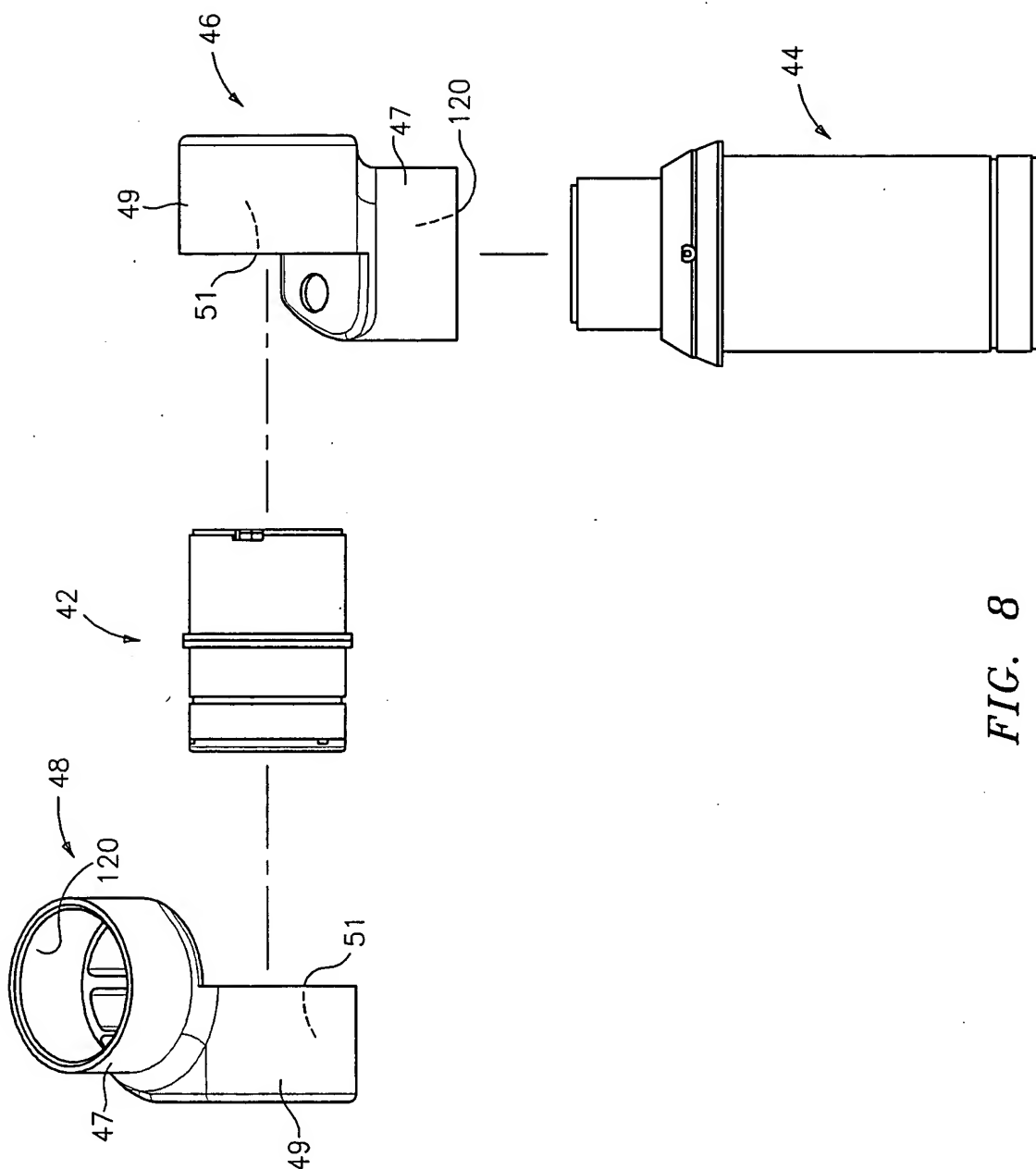


FIG. 8

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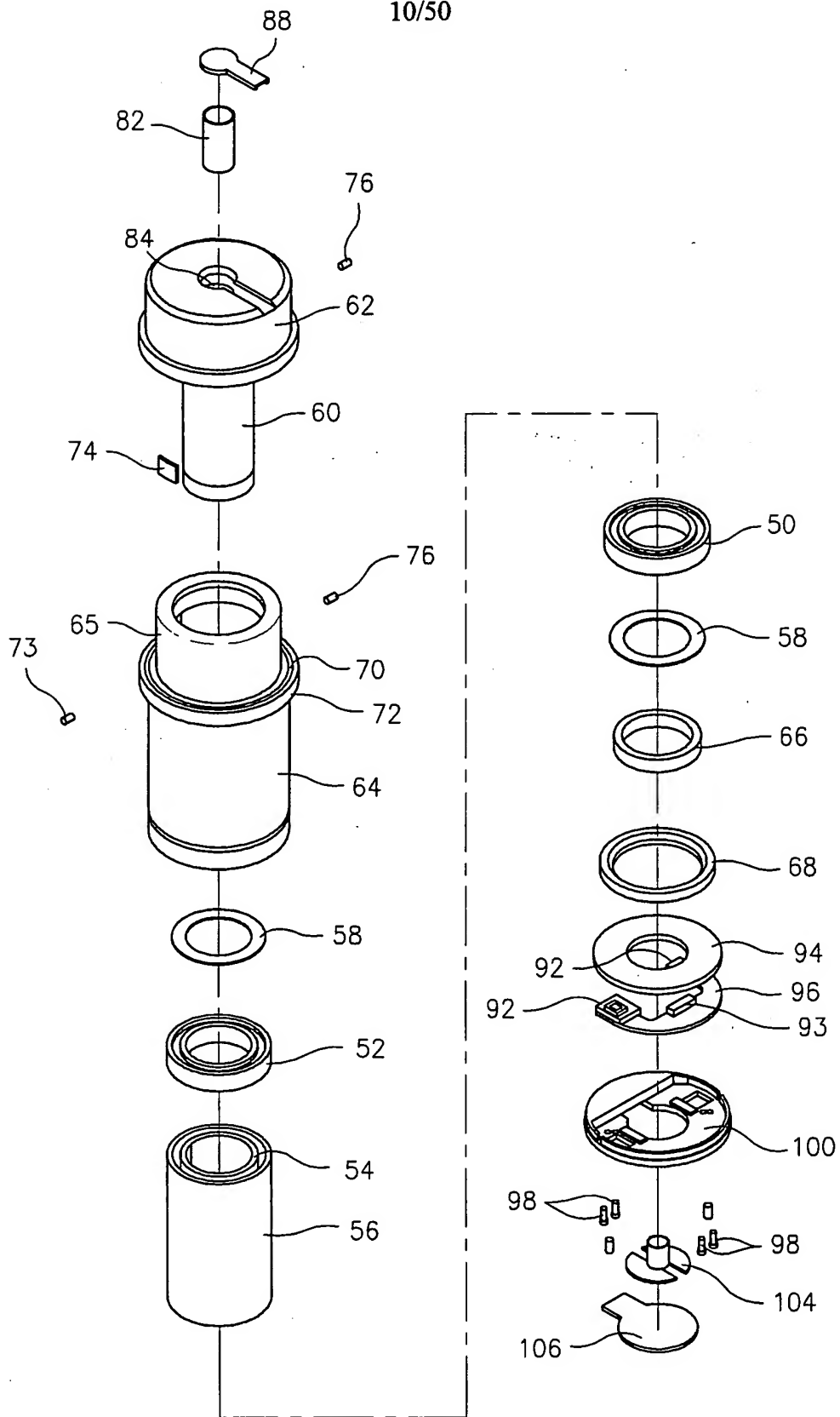


FIG. 9

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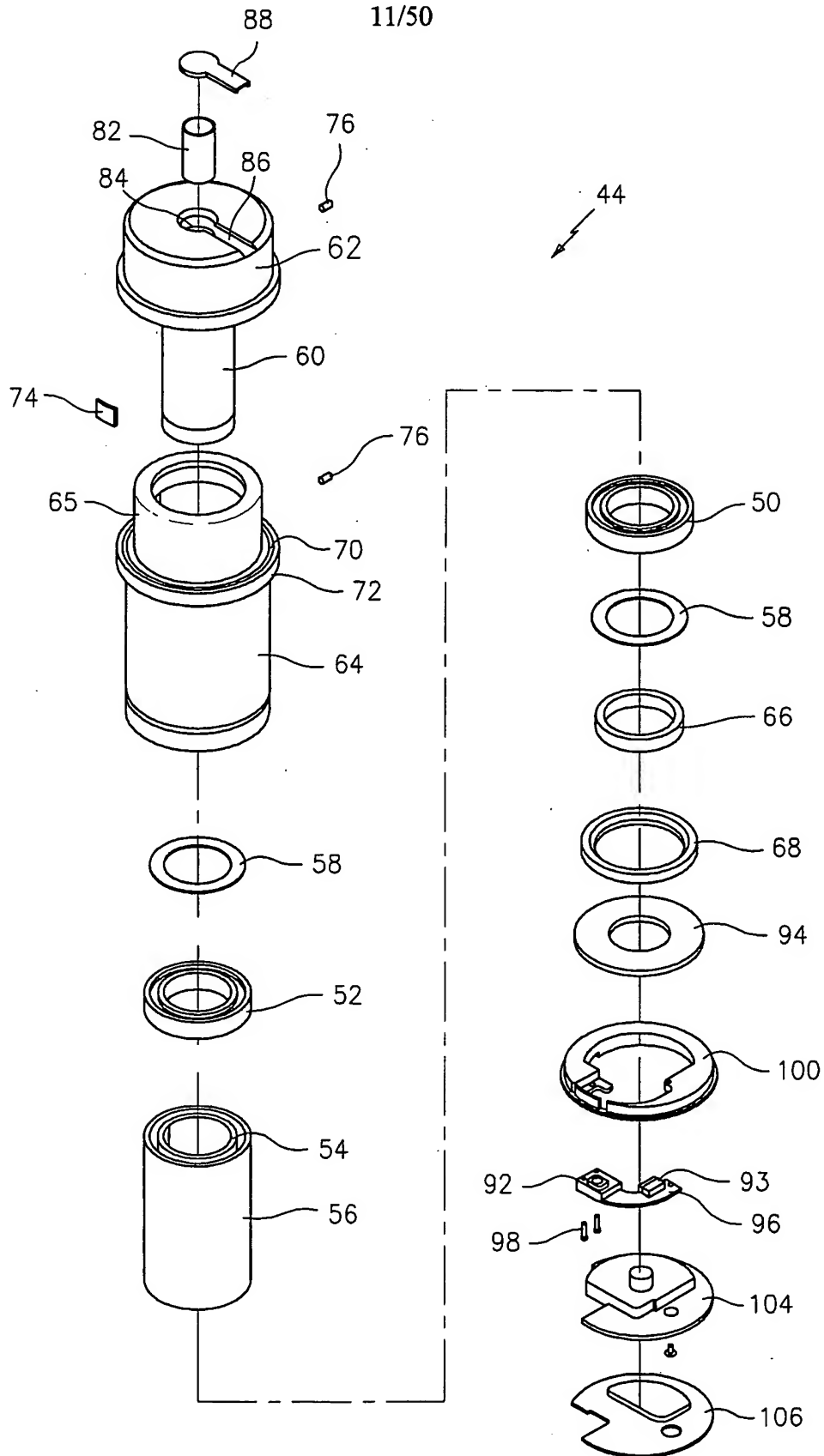


FIG. 9A

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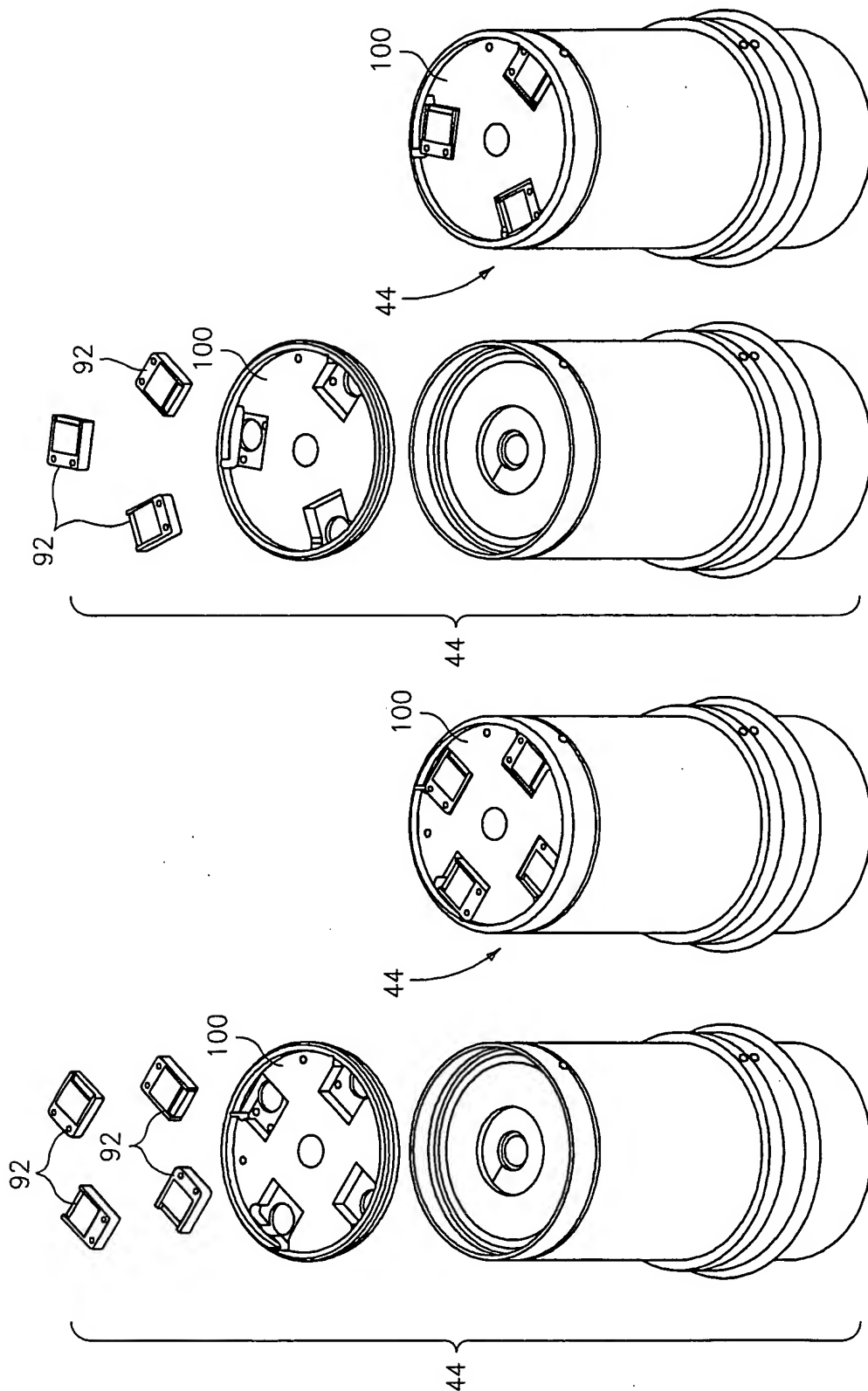


FIG. 9E

FIG. 9D

FIG. 9C

FIG. 9B

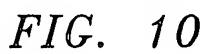


FIG. 10

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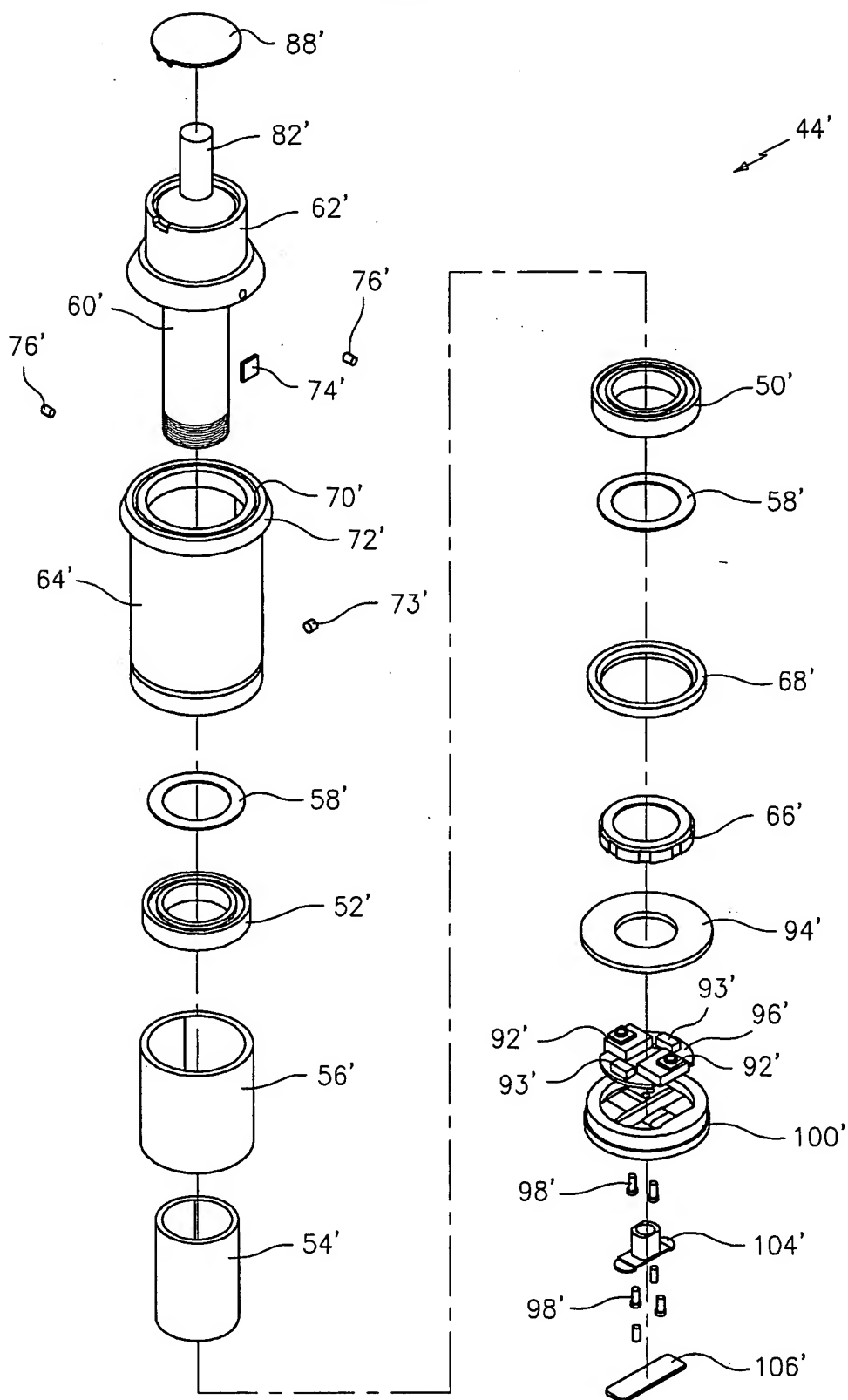


FIG. 11

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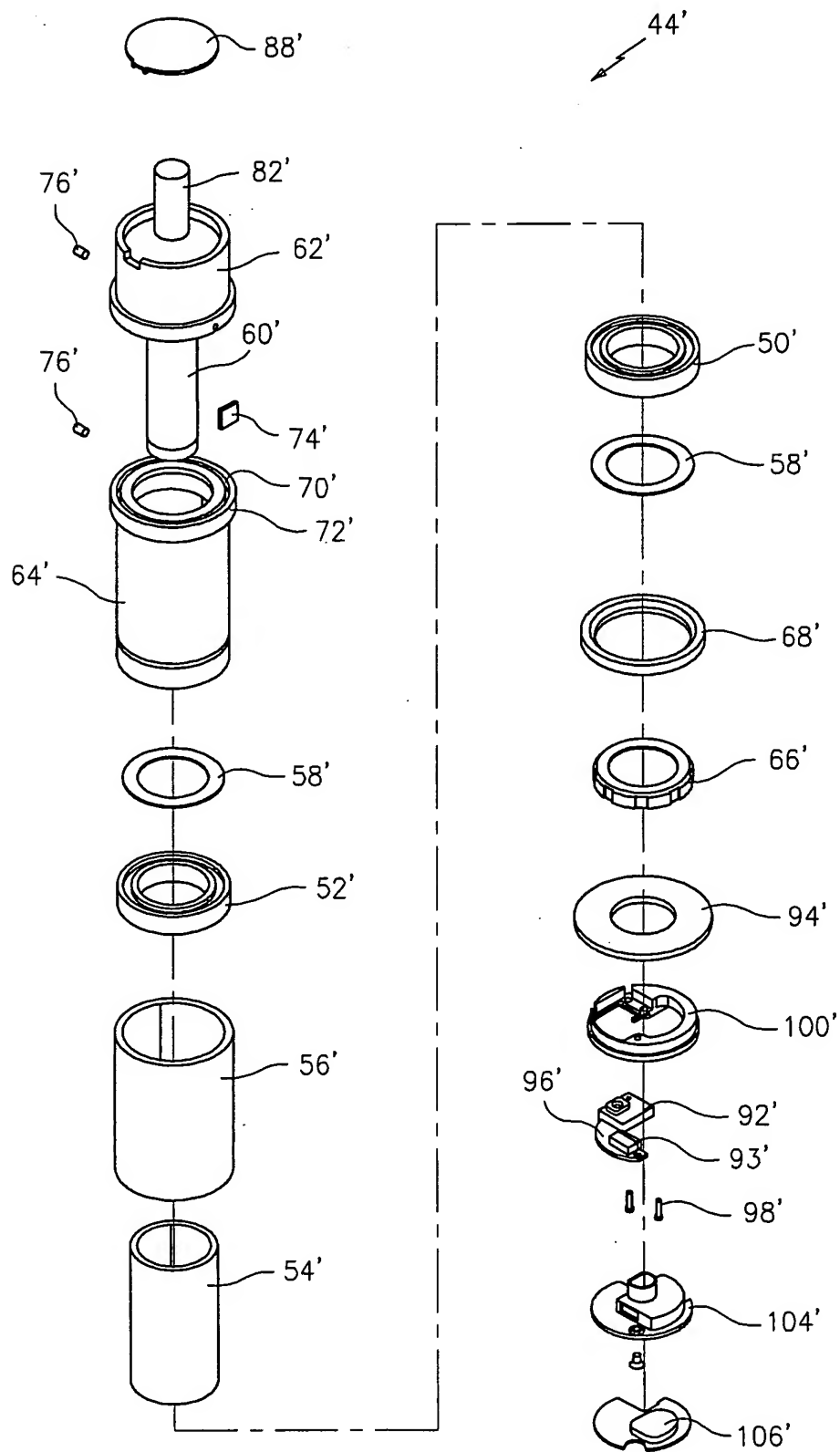


FIG. 11A

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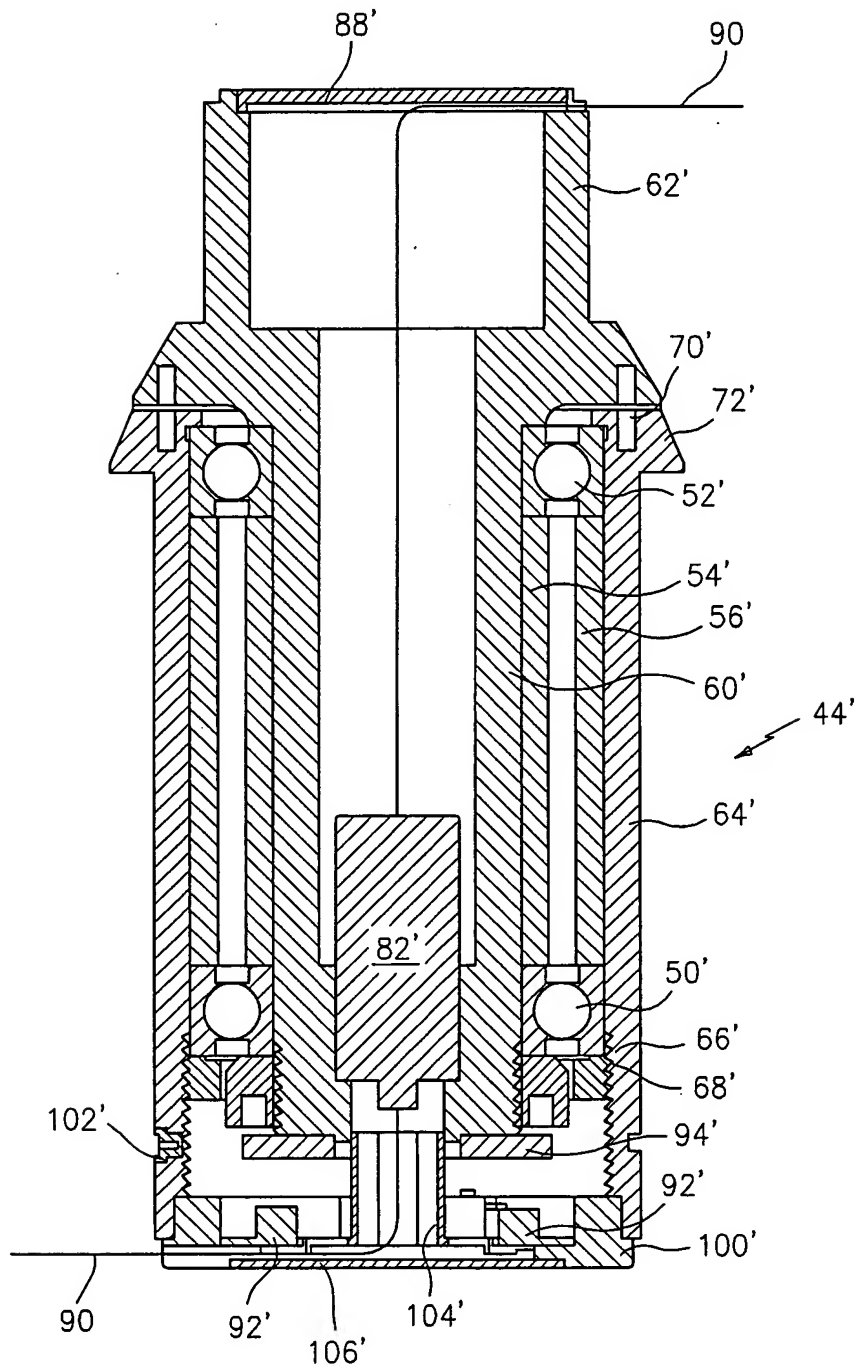


FIG. 12

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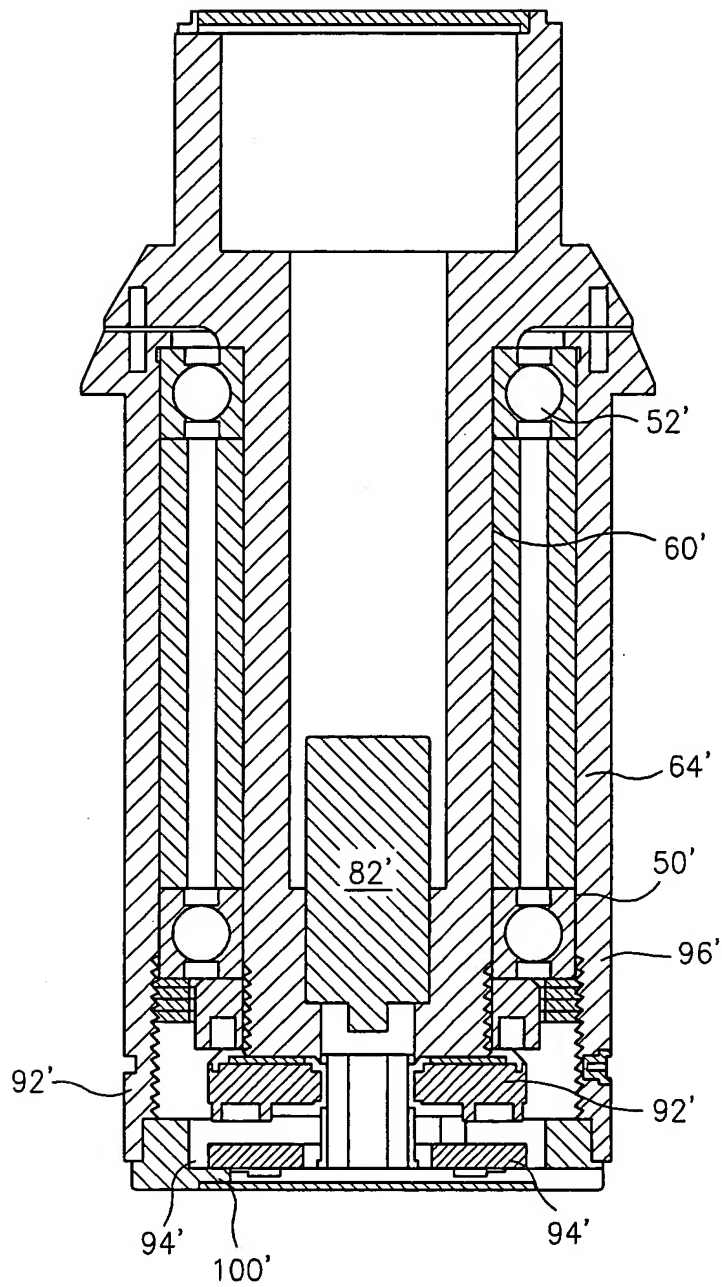


FIG. 12A

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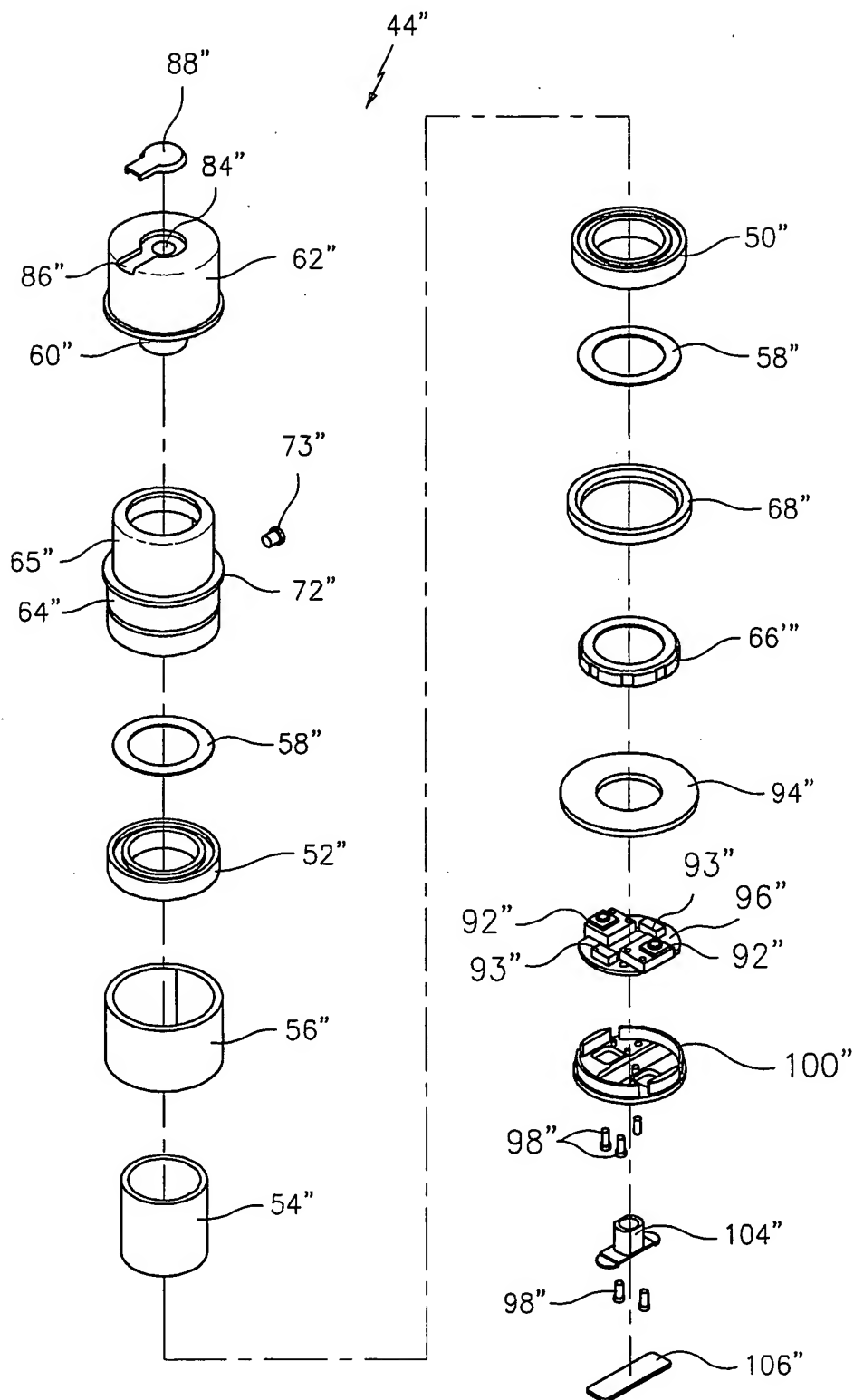


FIG. 13

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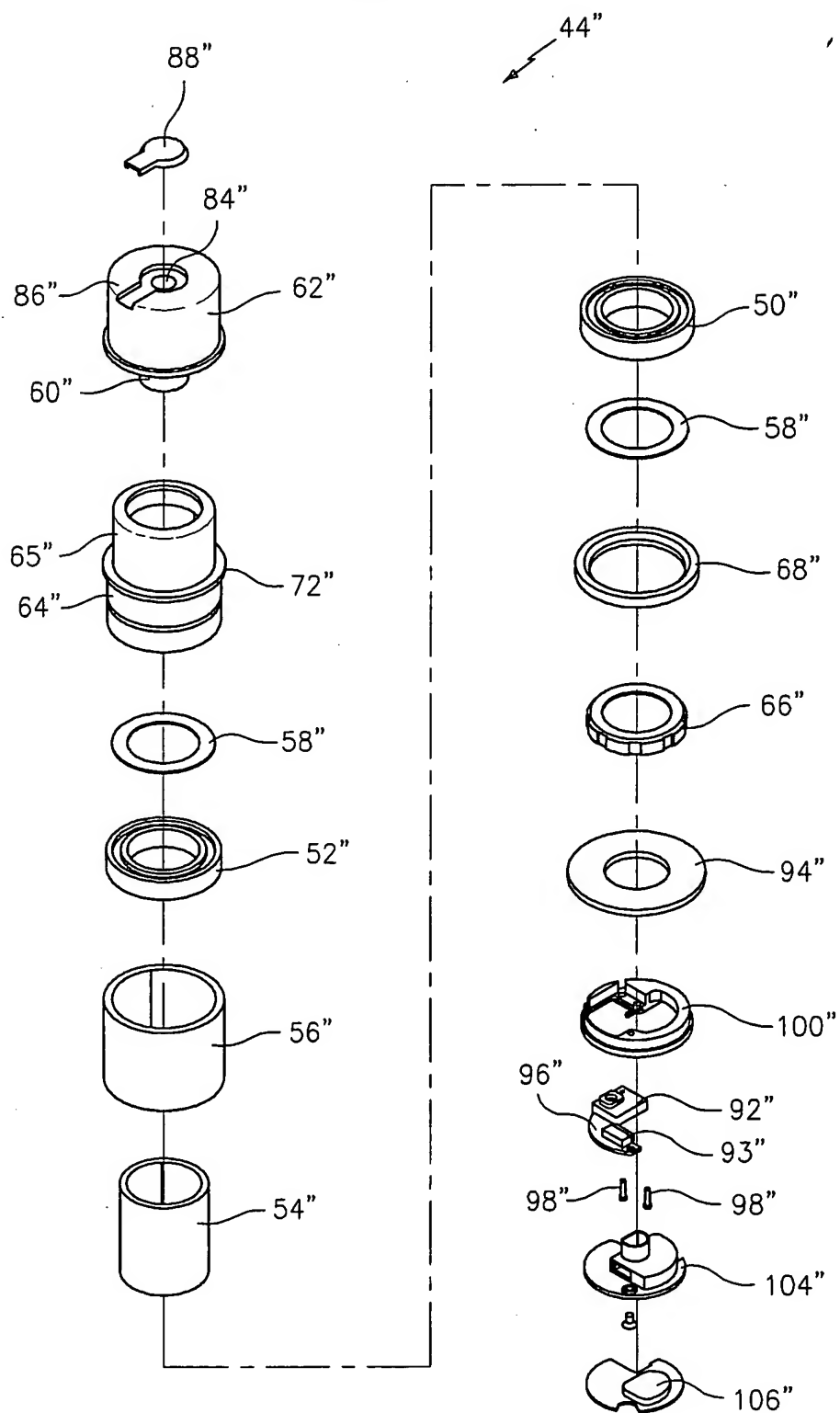


FIG. 13A

METHOD FOR PROVIDING SENSORY FEEDBACK TO THE
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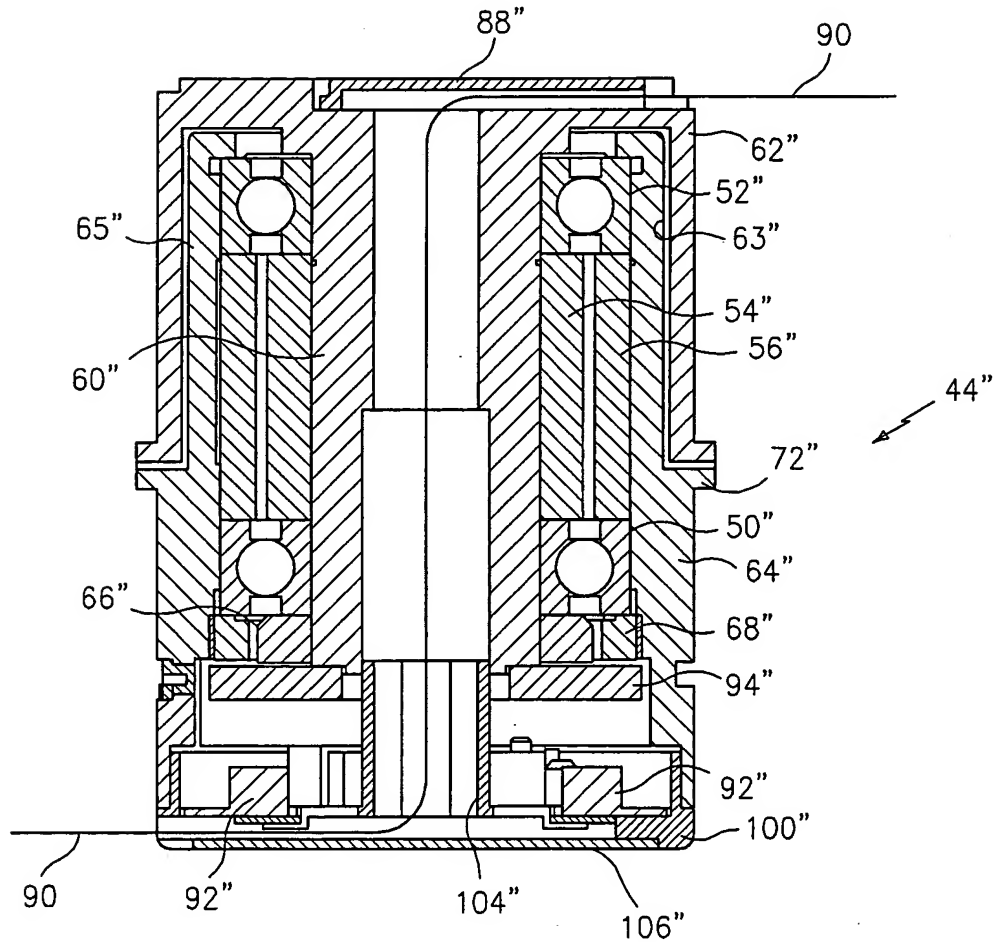


FIG 14

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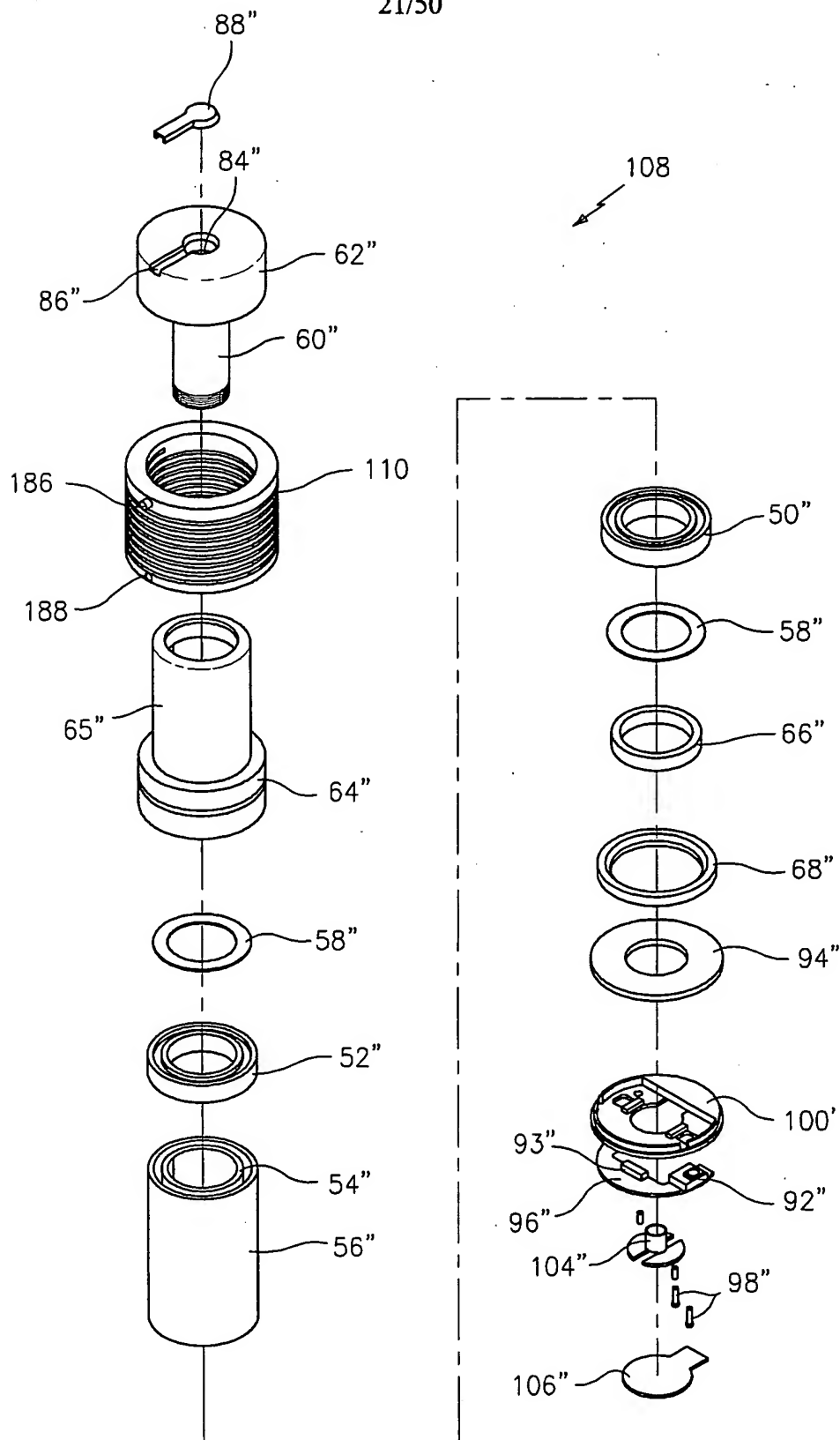


FIG. 15

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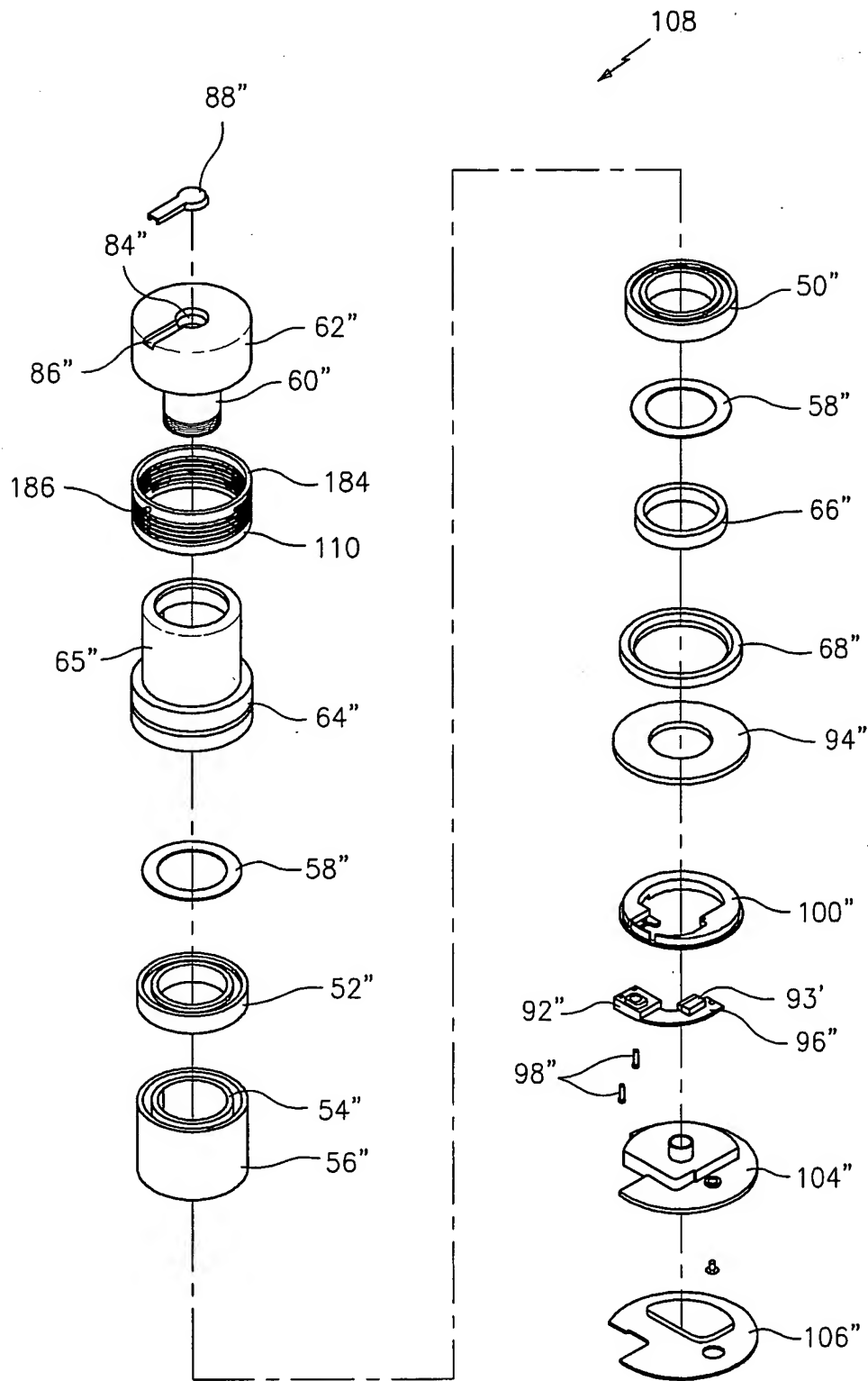


FIG. 15A

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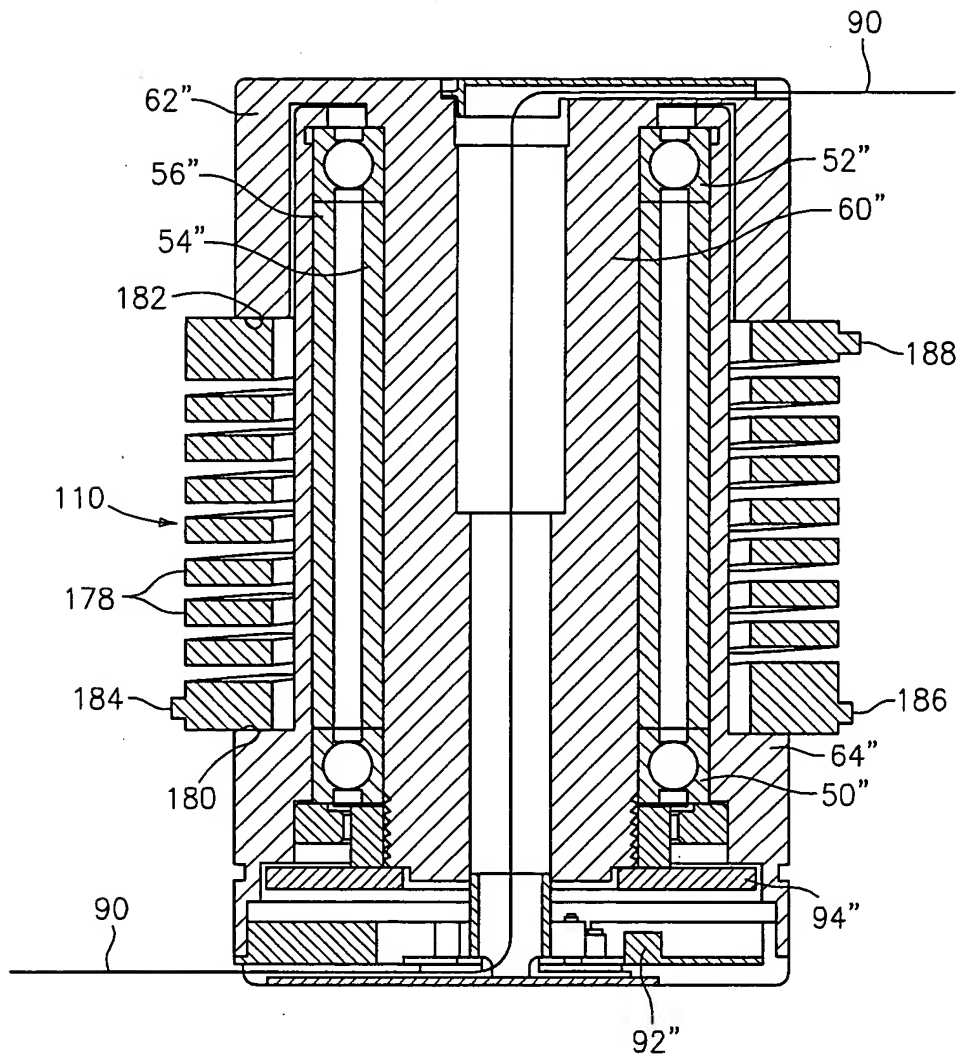


FIG. 16

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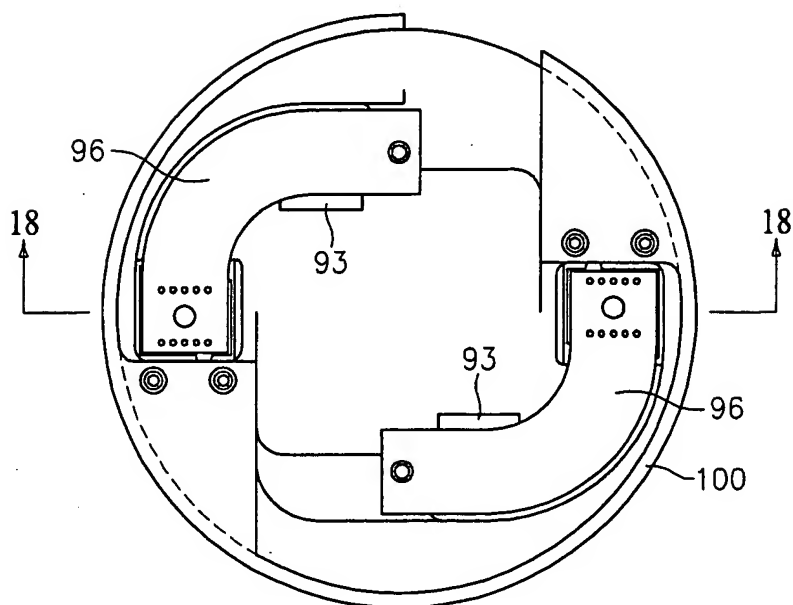


FIG. 17

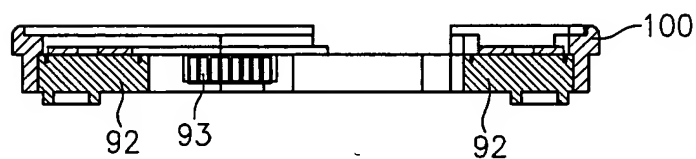


FIG. 18

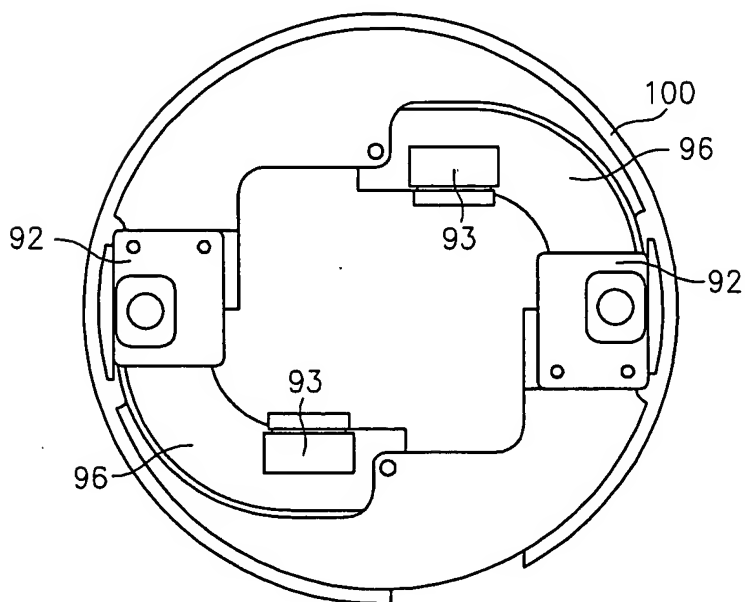


FIG. 19

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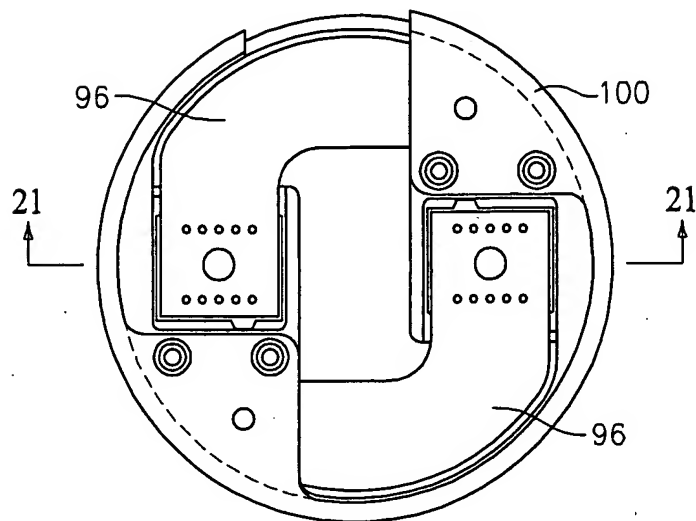


FIG. 20

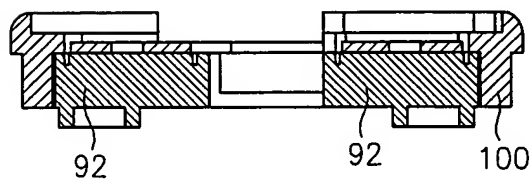


FIG. 21

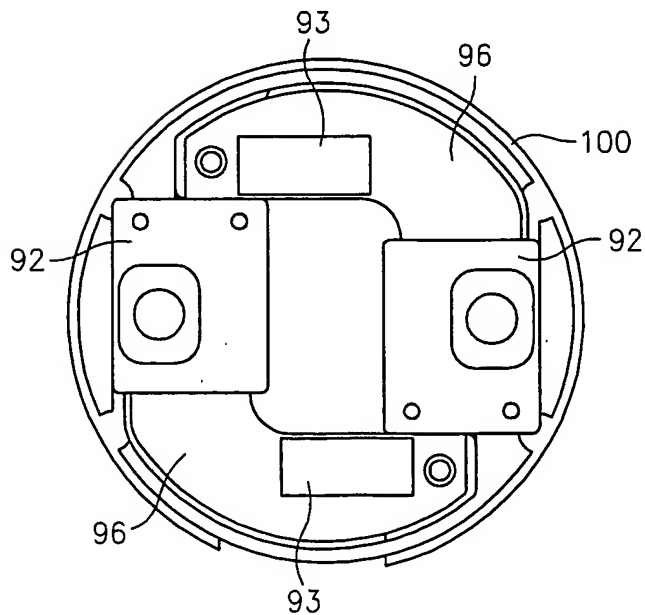


FIG. 22

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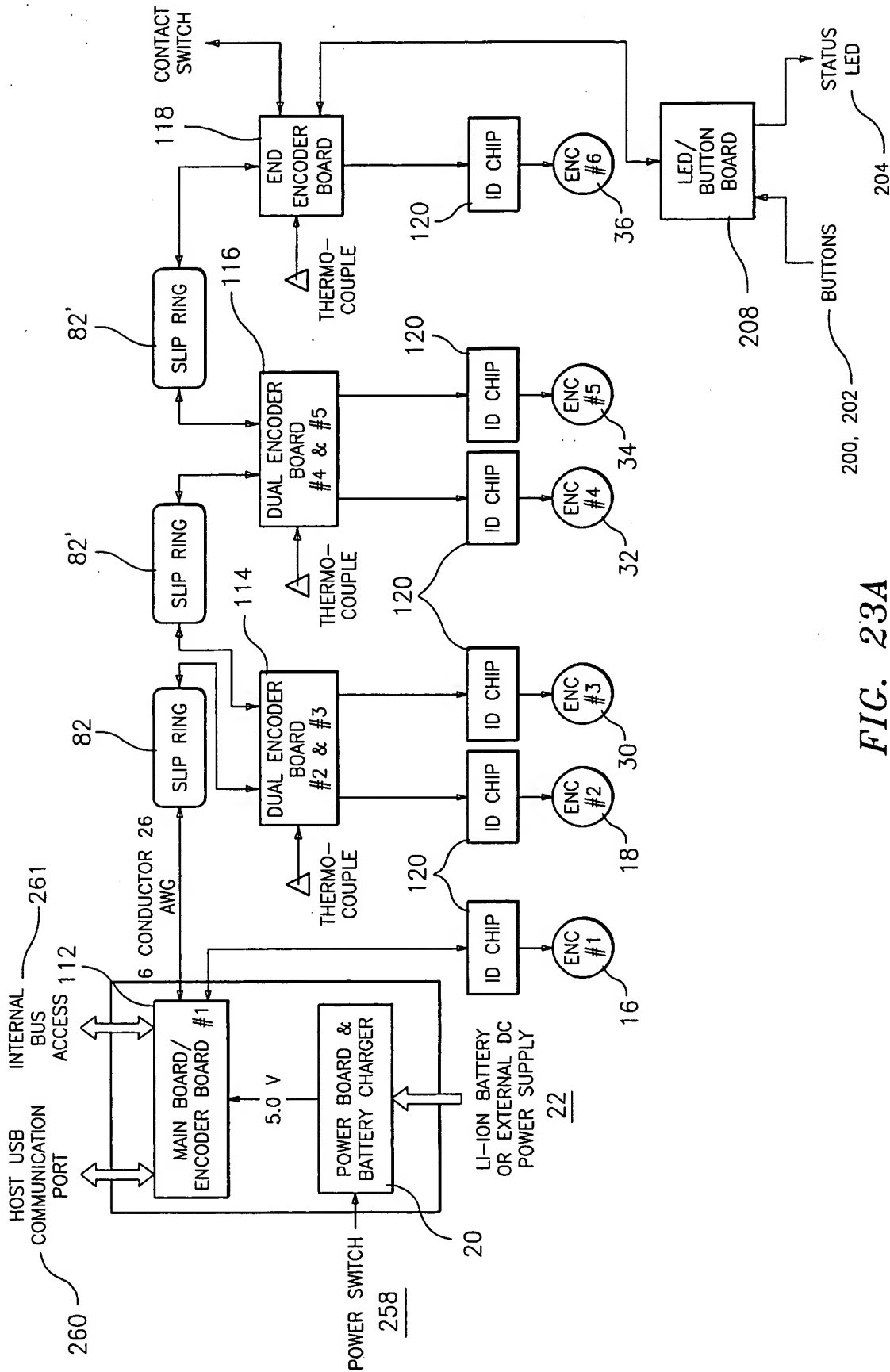


FIG. 23A

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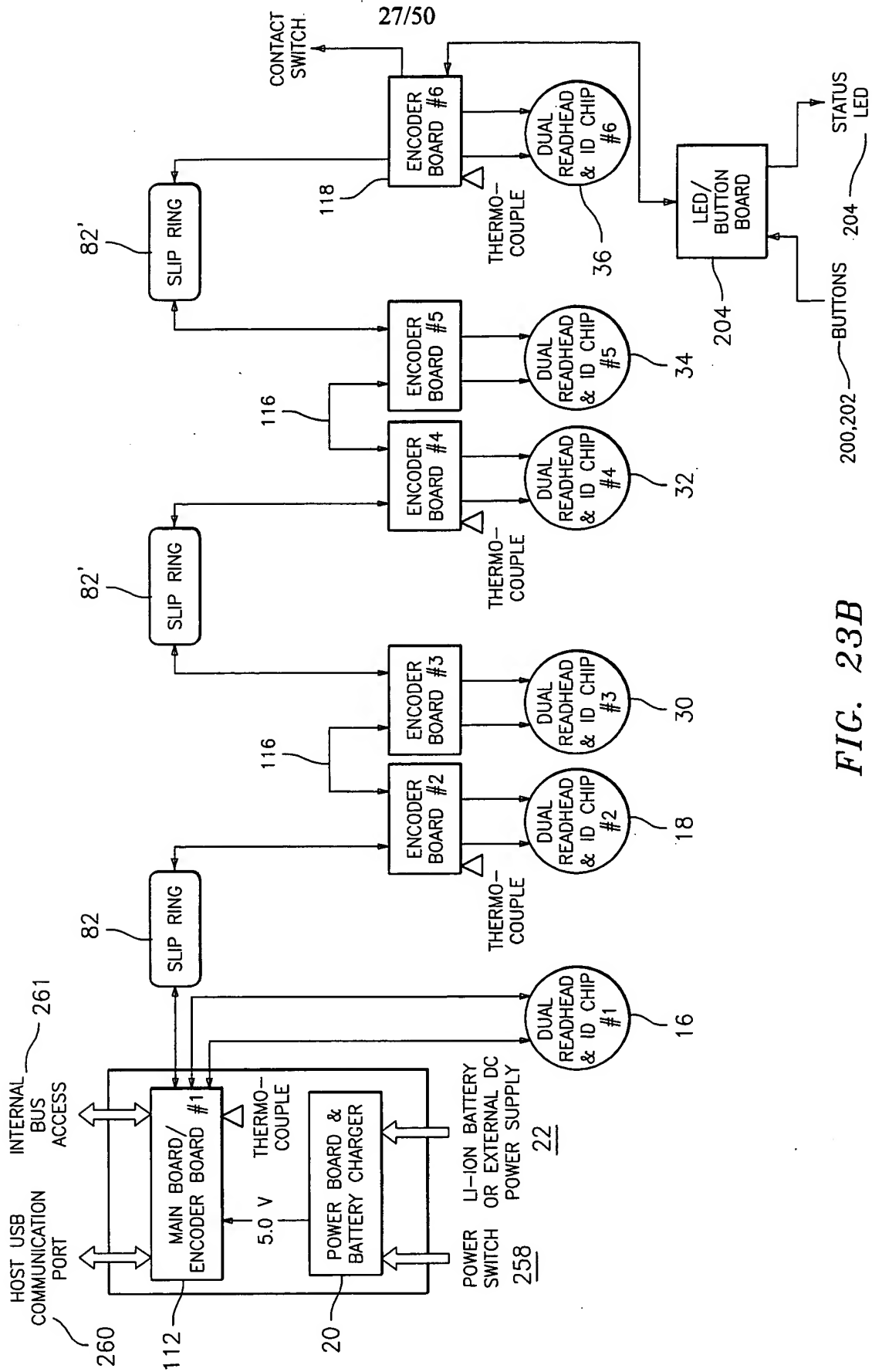


FIG. 23B

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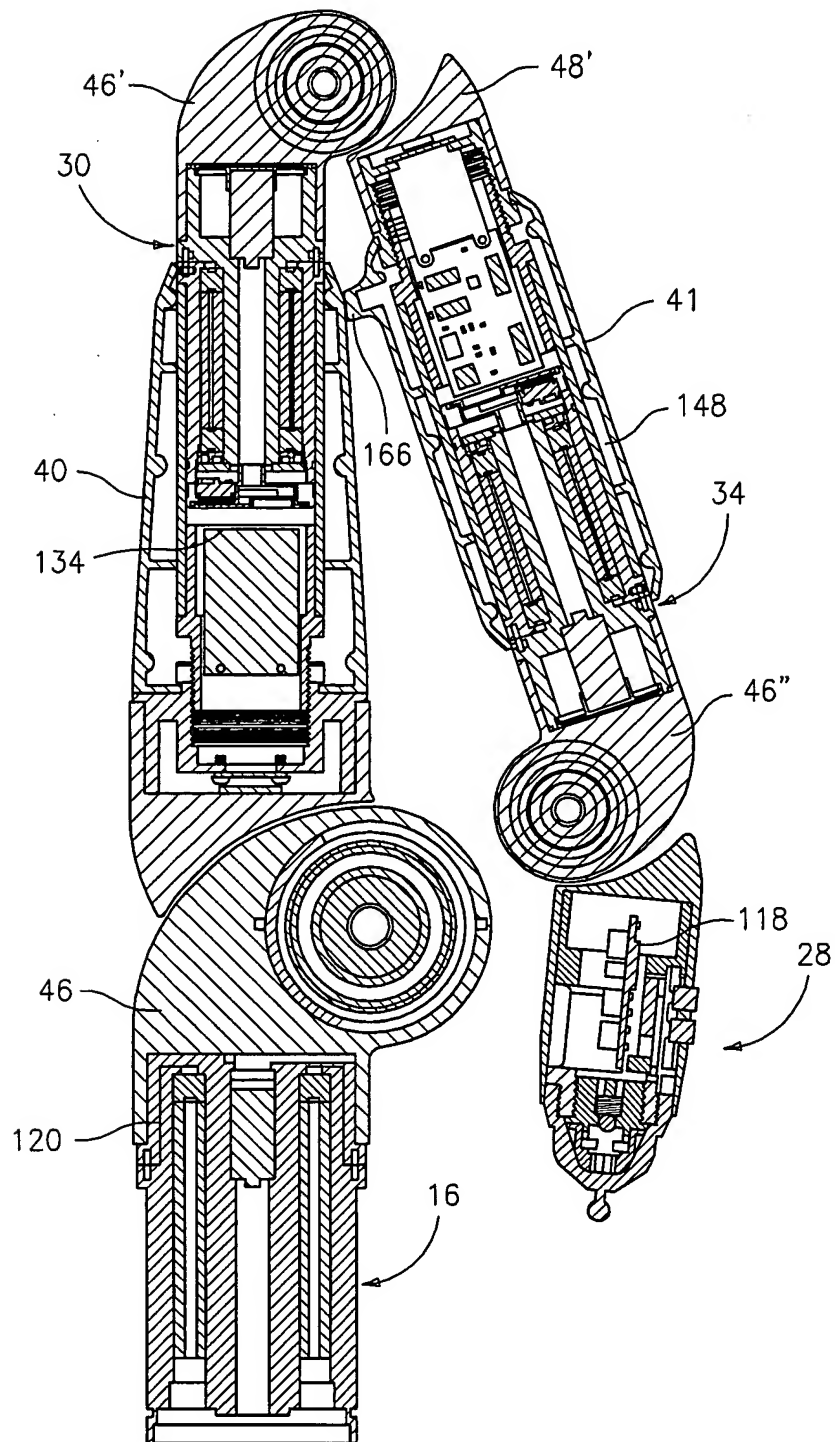


FIG. 24

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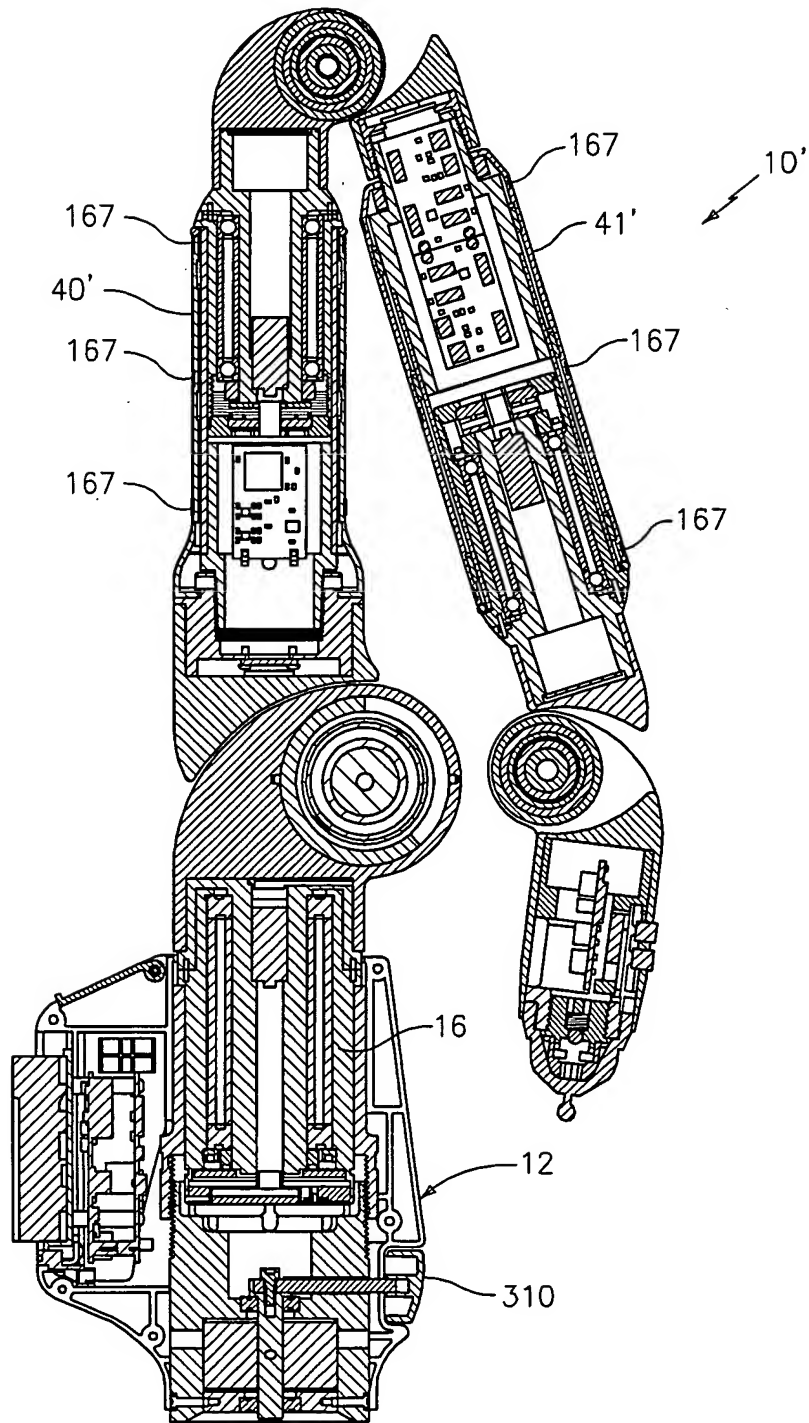


FIG. 24A

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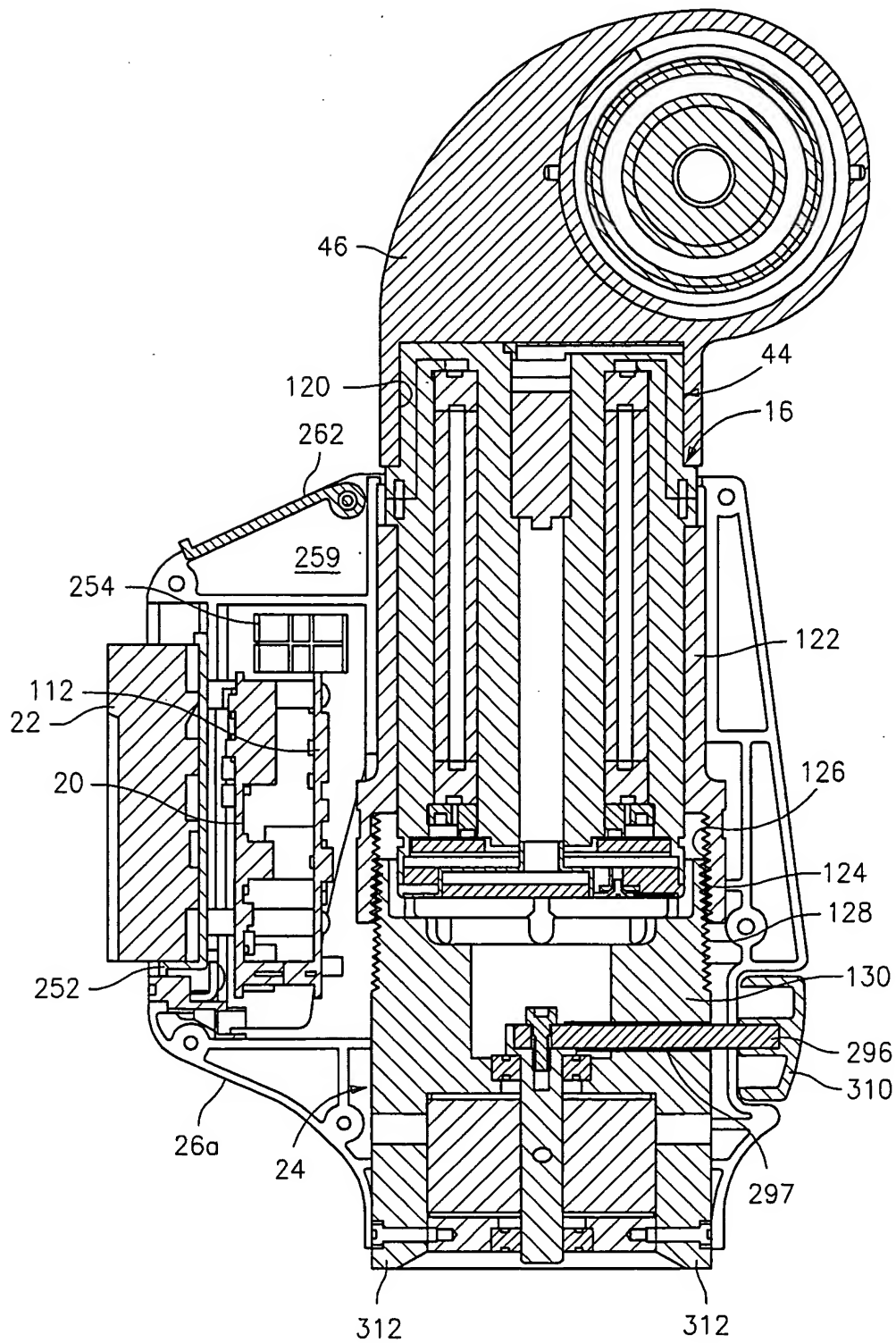


FIG. 25

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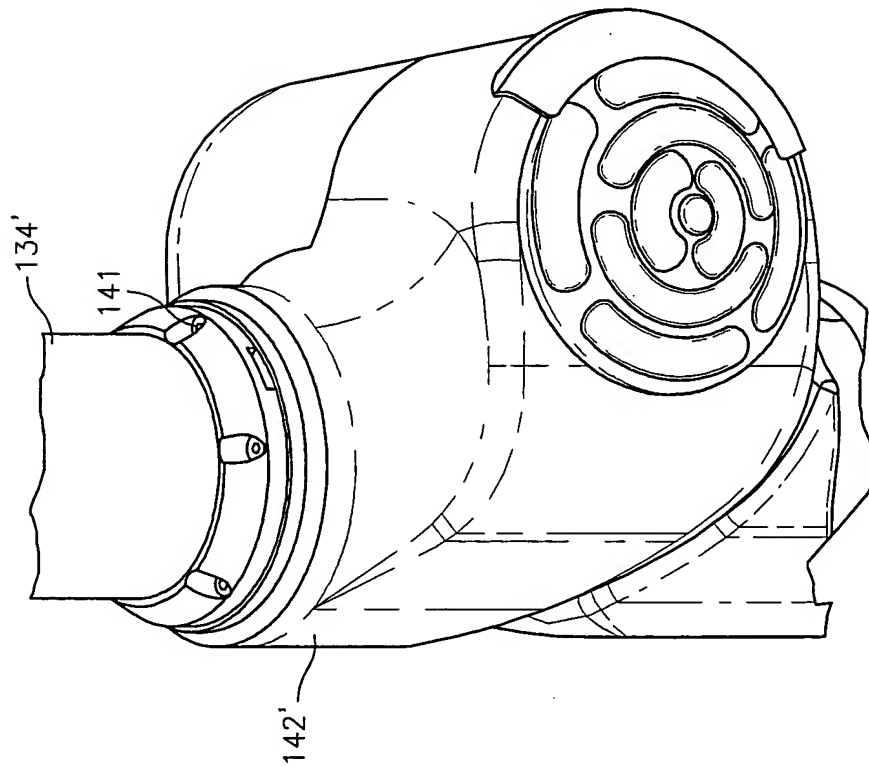


FIG. 25A

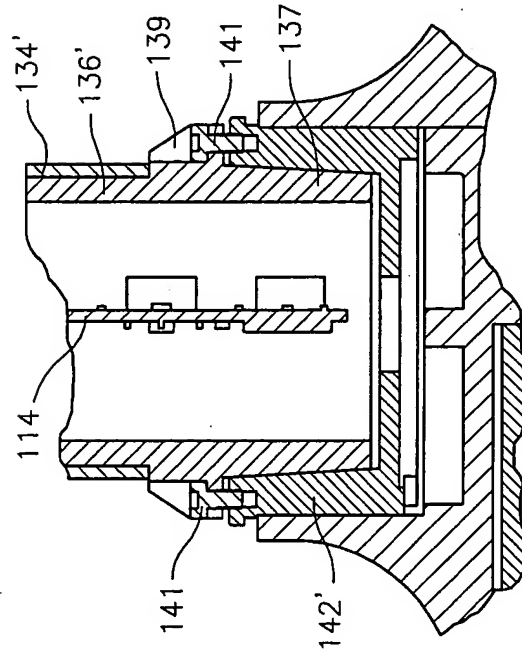


FIG. 25B

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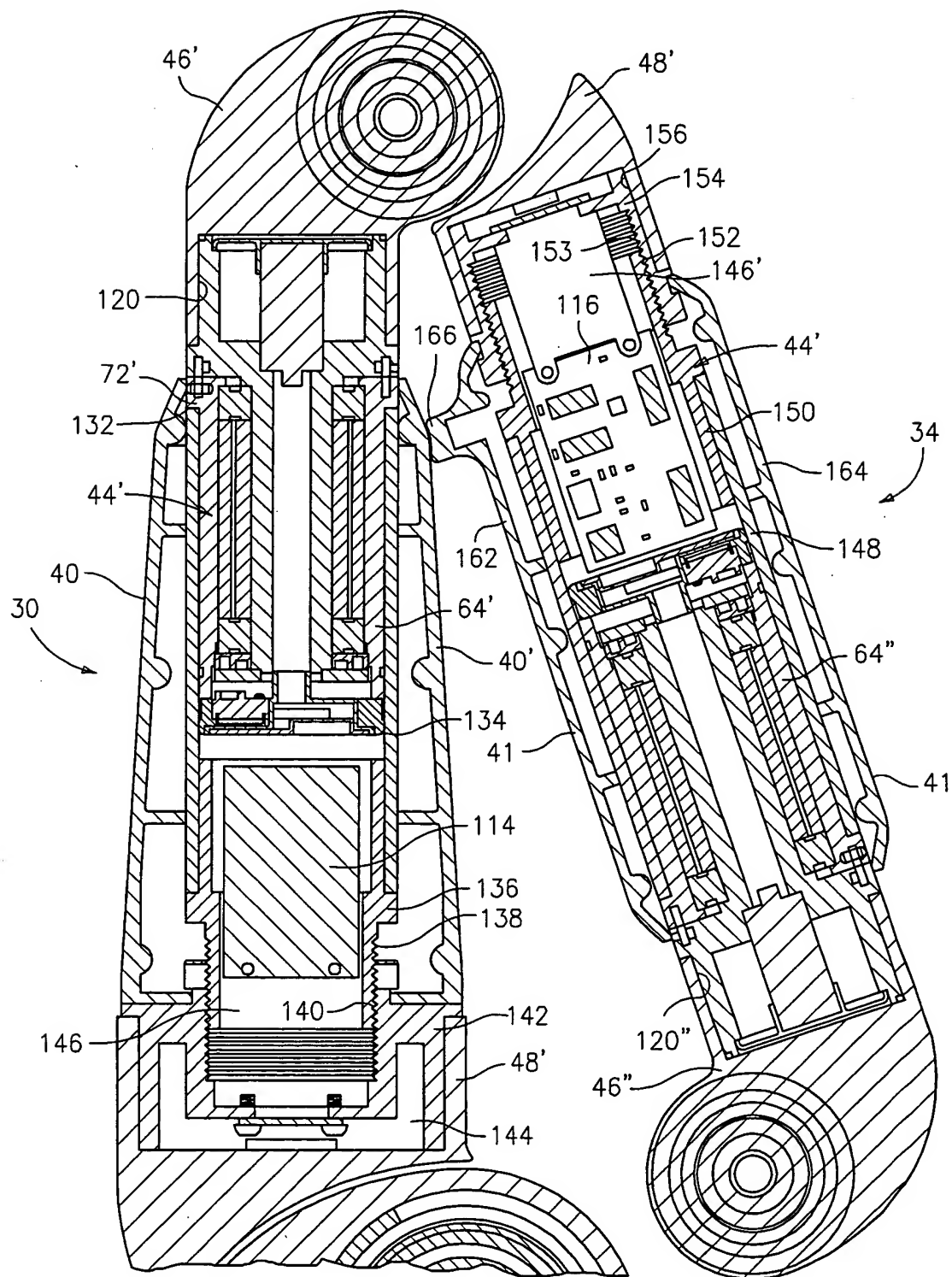


FIG. 26

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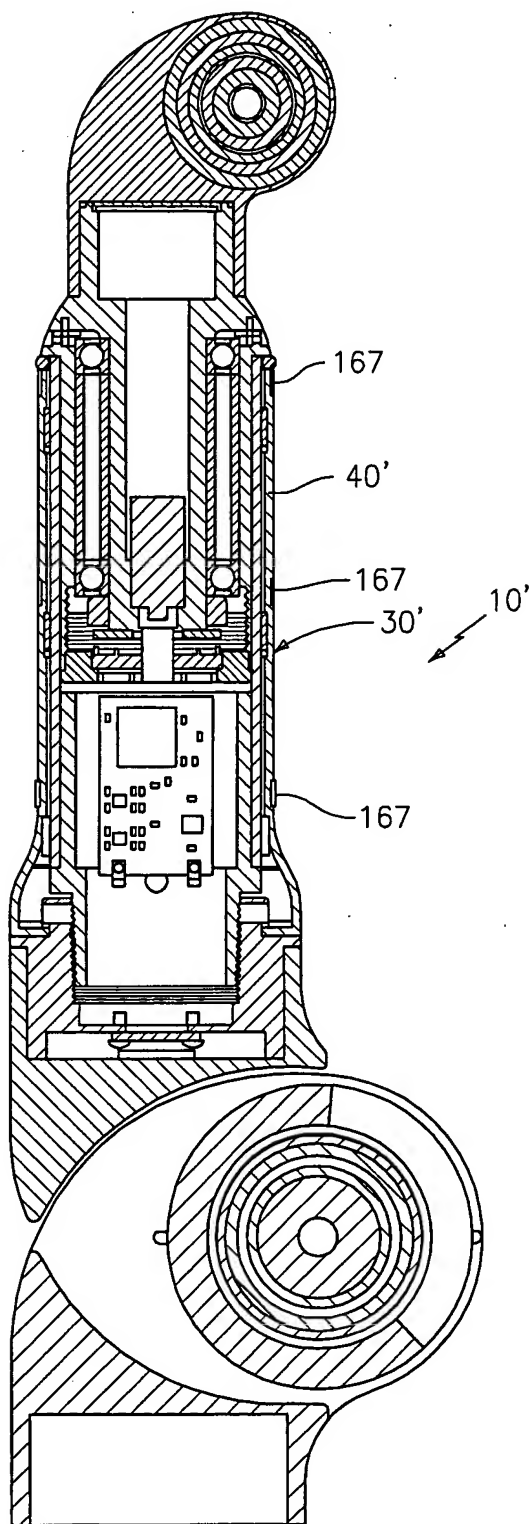


FIG. 26A

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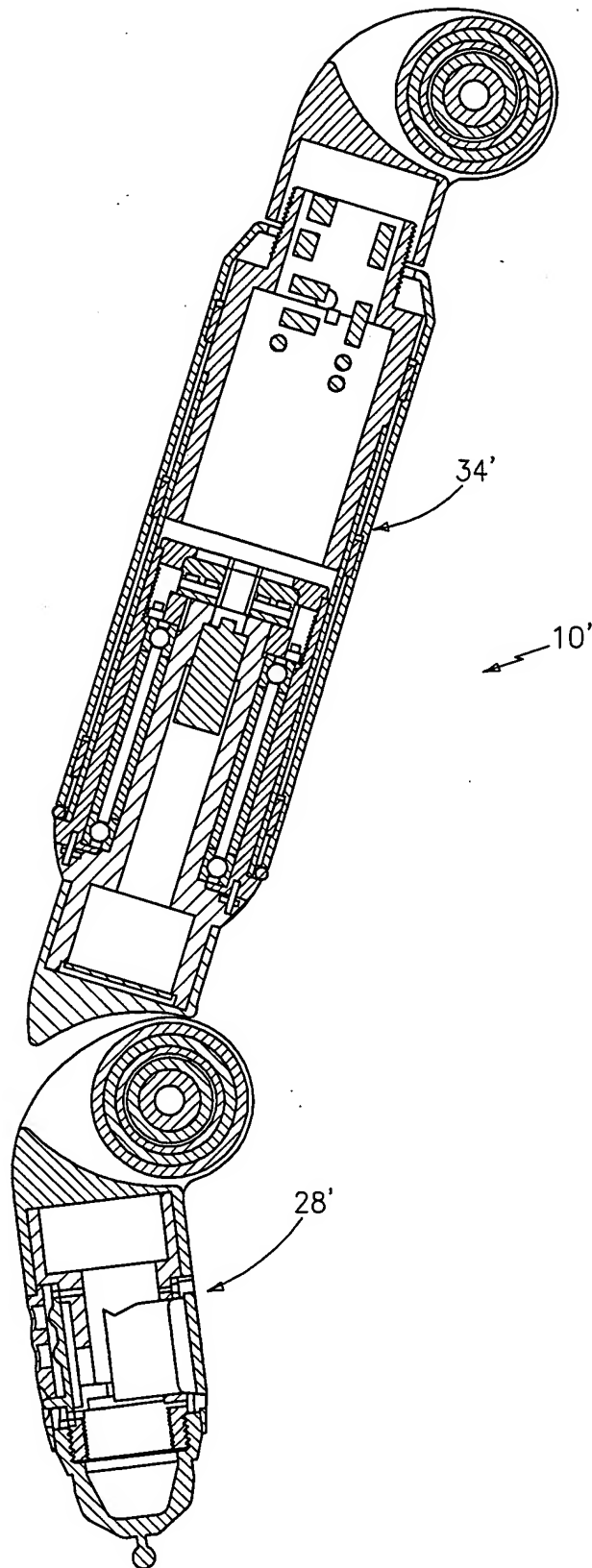


FIG. 26B

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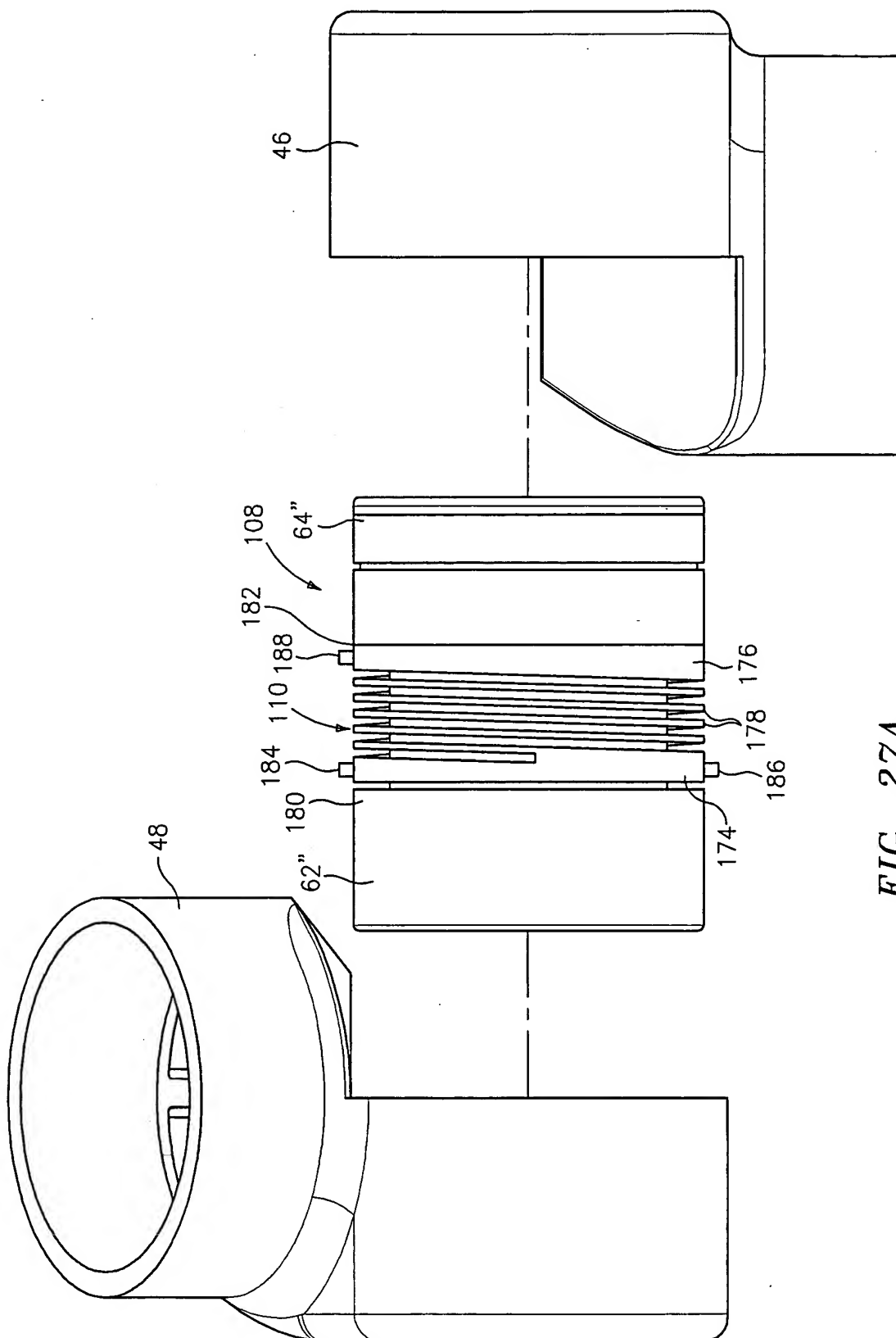


FIG. 27A

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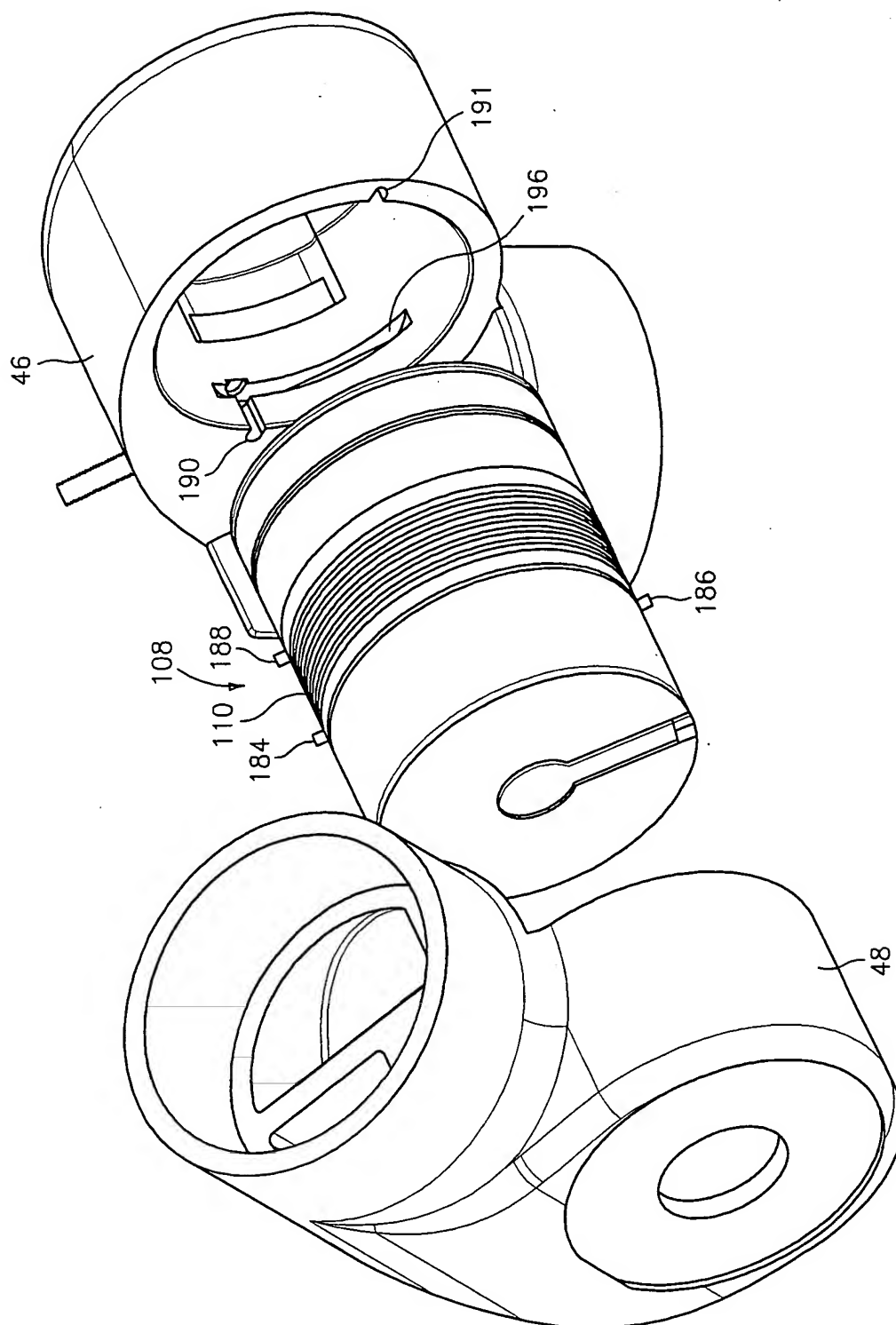


FIG. 27B

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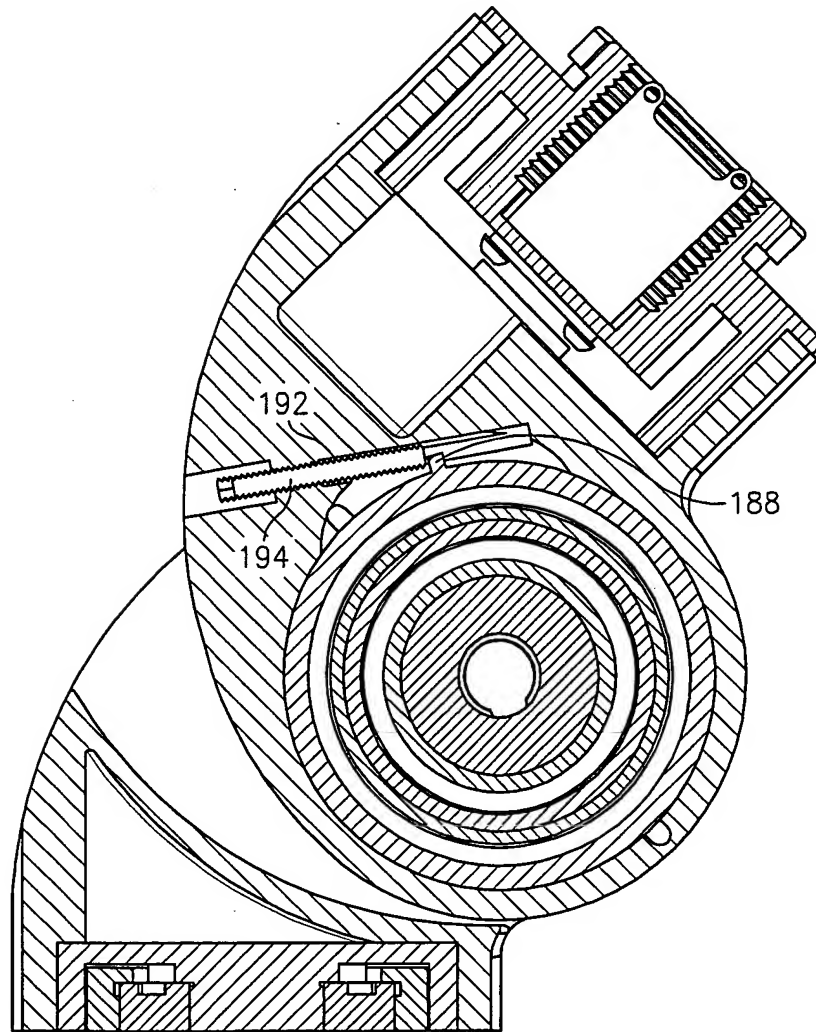


FIG. 28

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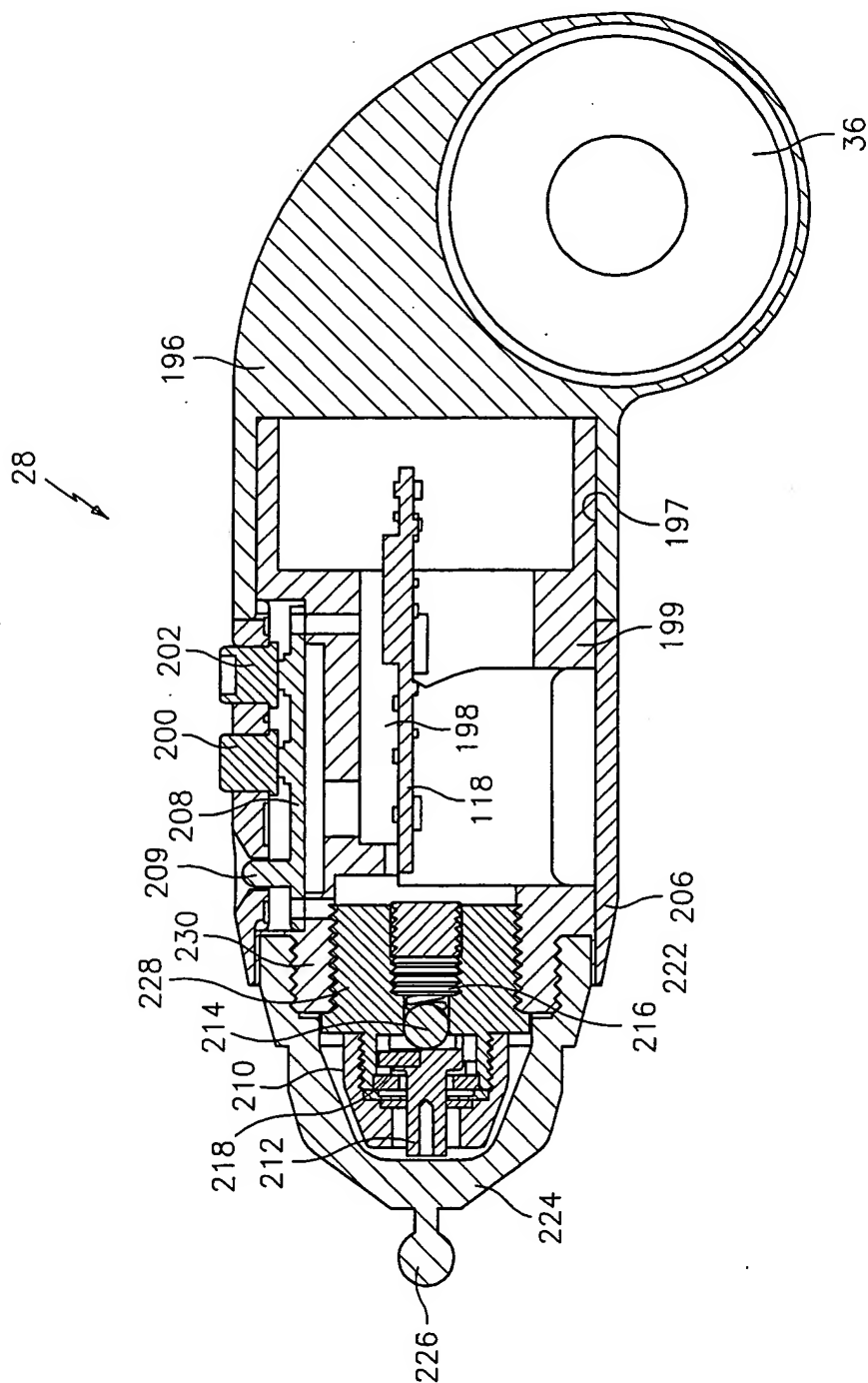


FIG. 29

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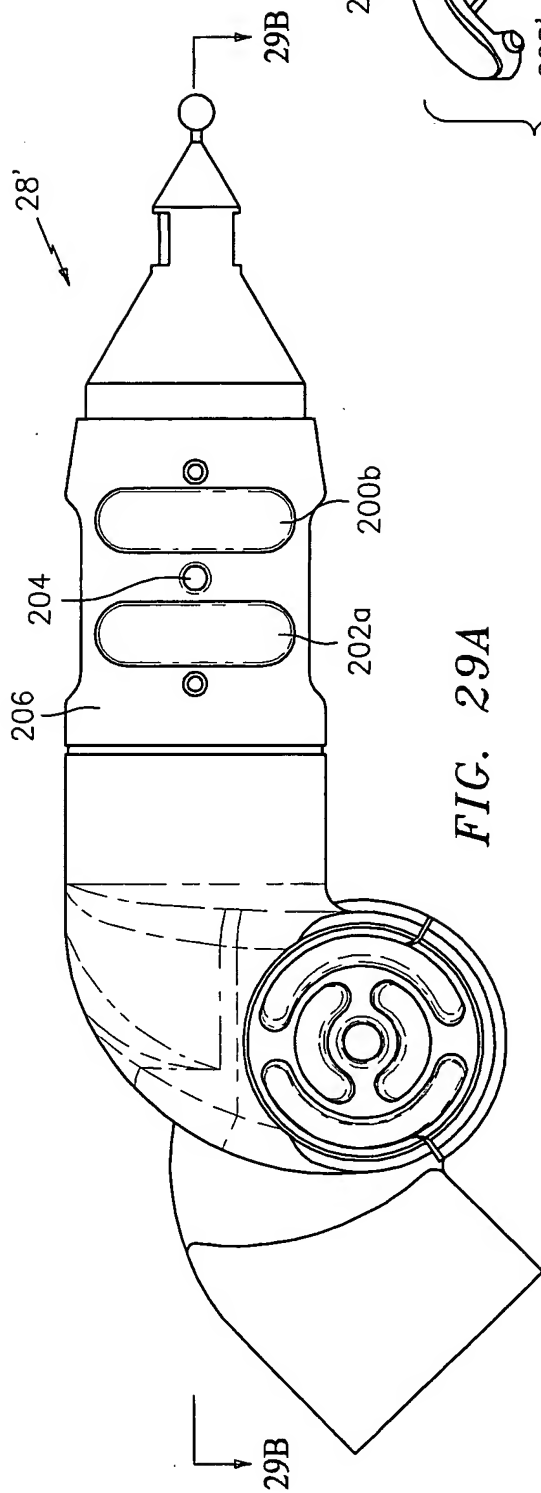


FIG. 29A

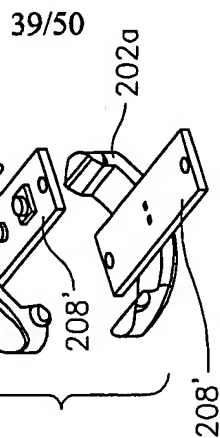


FIG. 29C

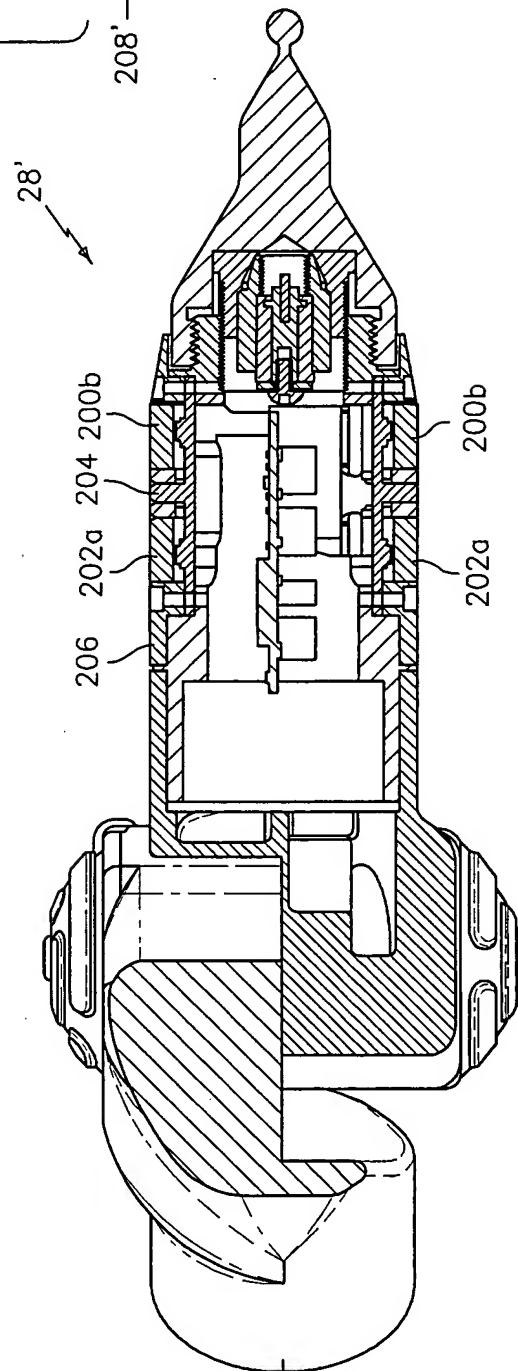


FIG. 29B

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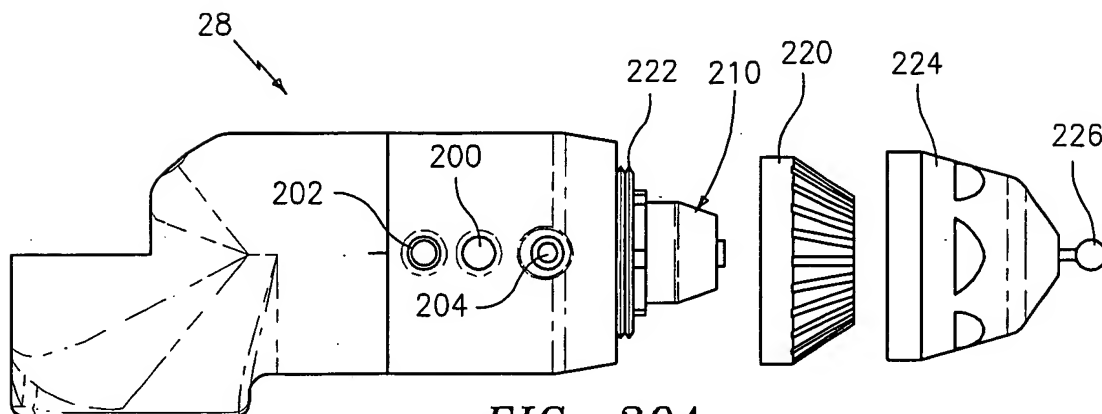


FIG. 30A

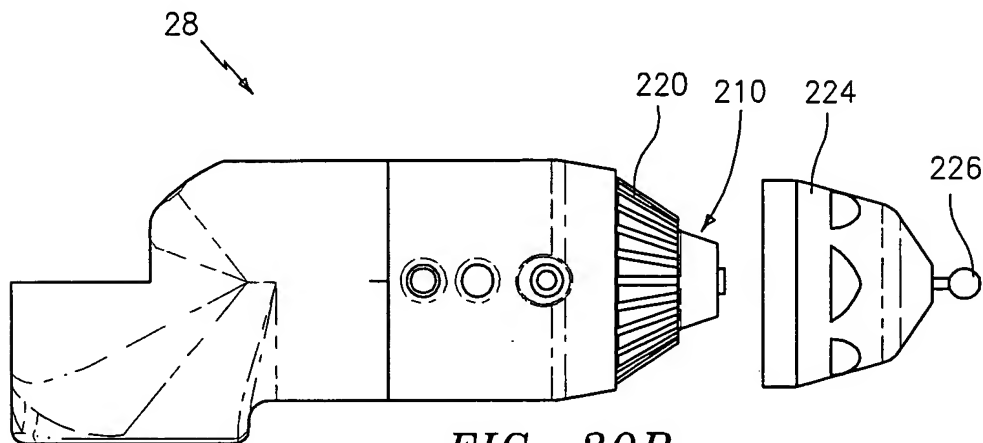


FIG. 30B

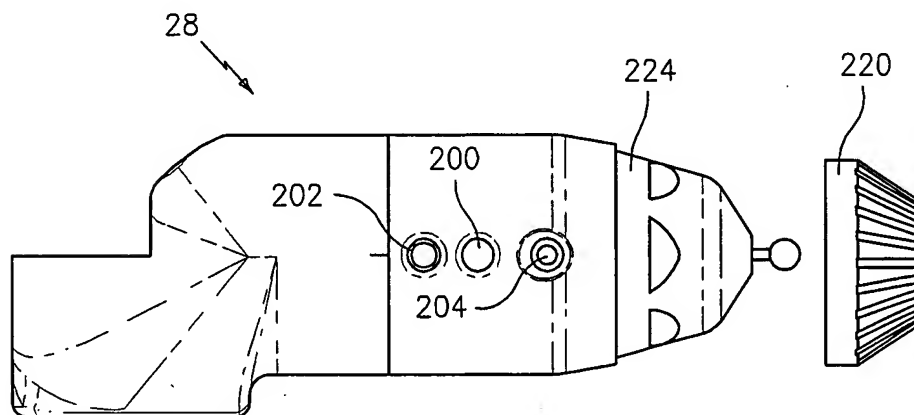


FIG. 30C

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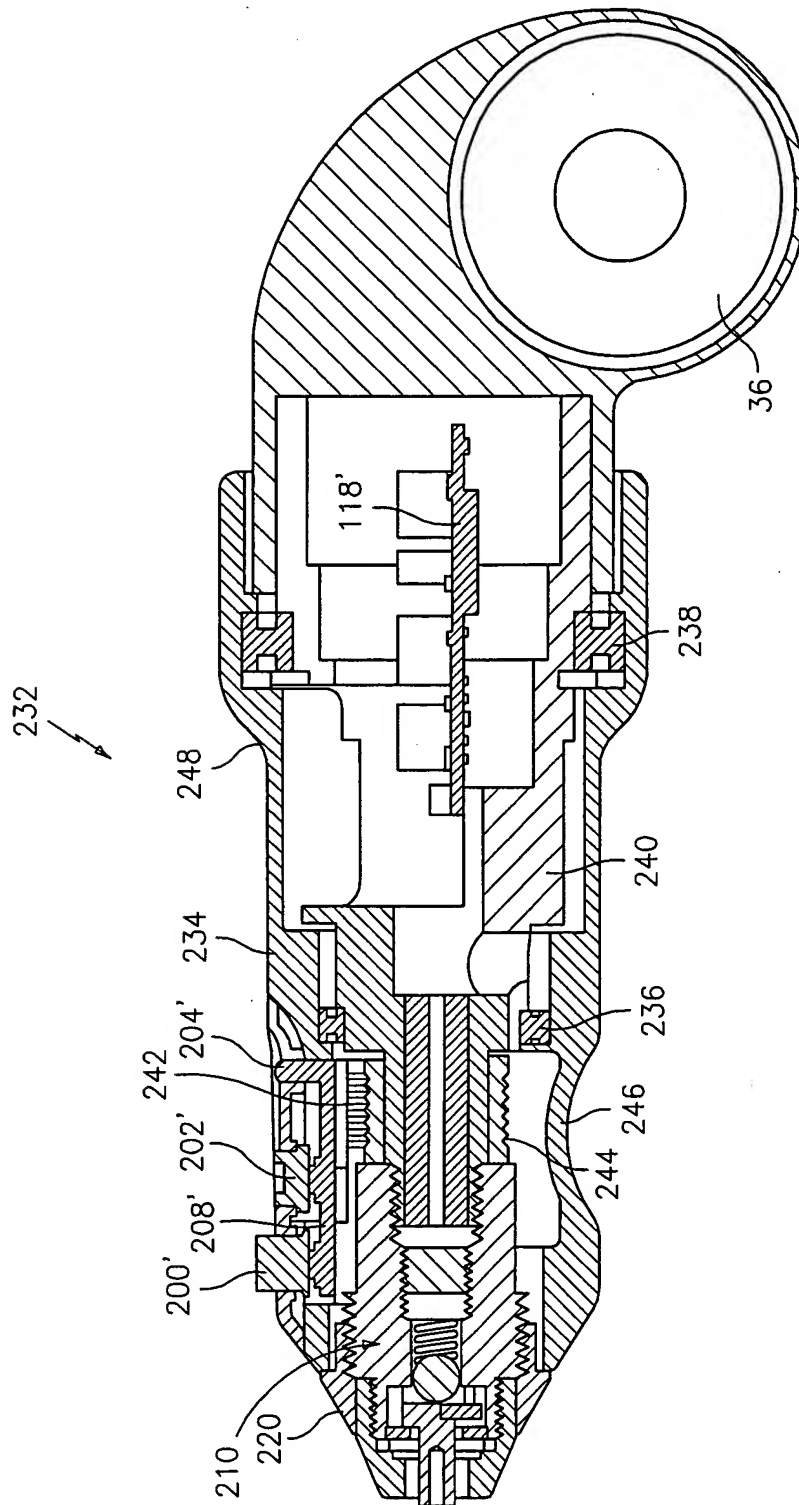


FIG. 31

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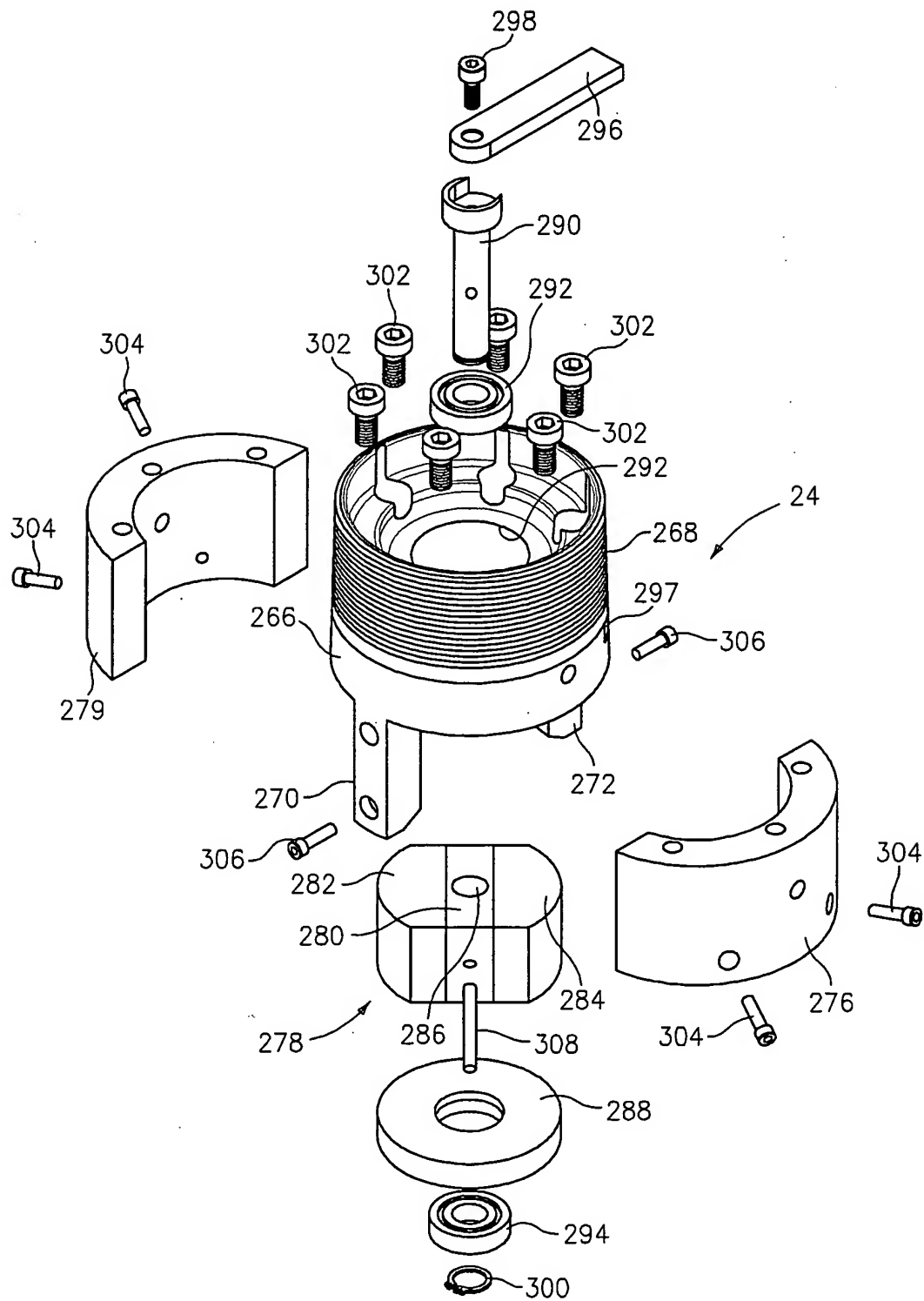


FIG. 32

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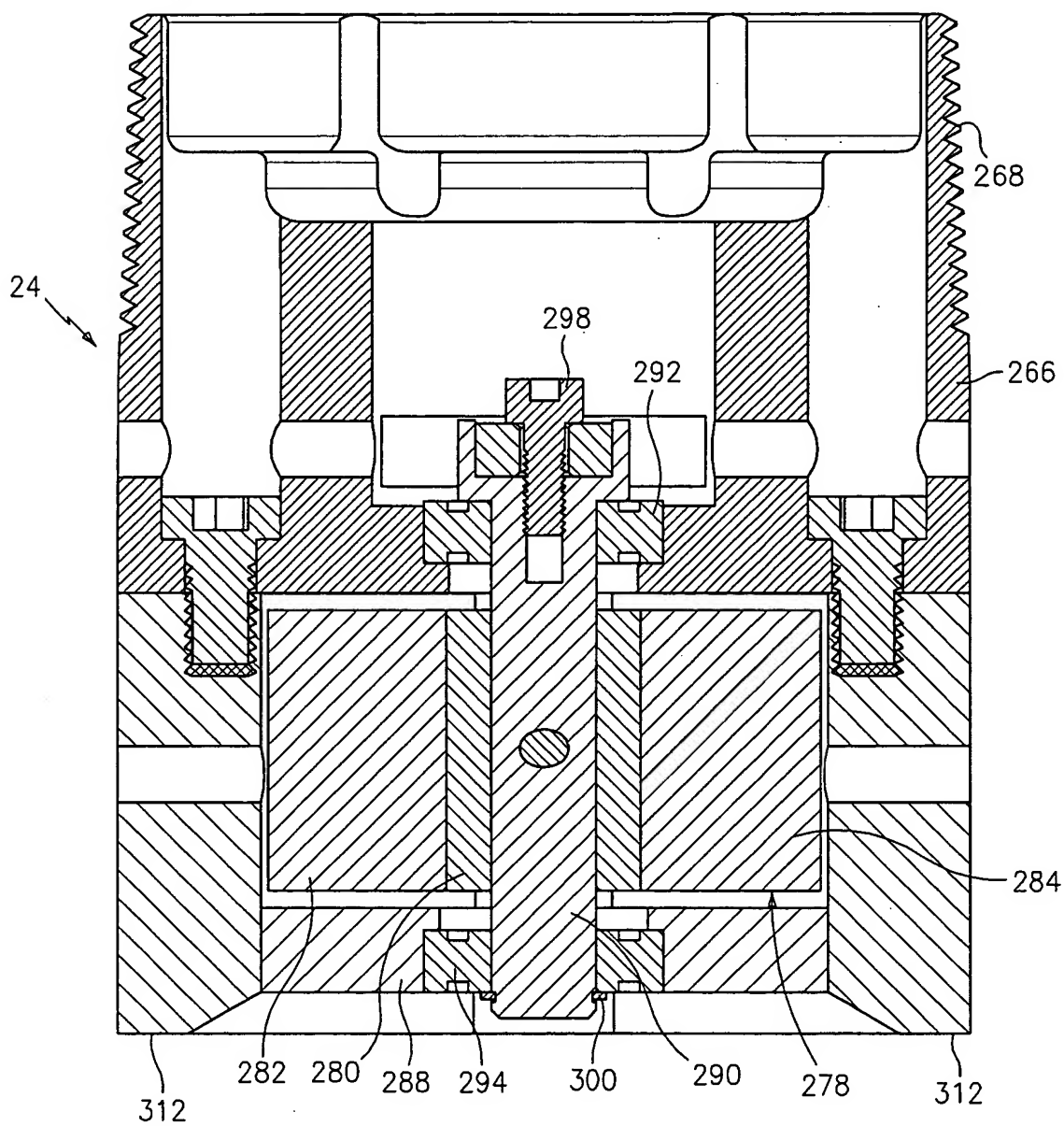


FIG. 33

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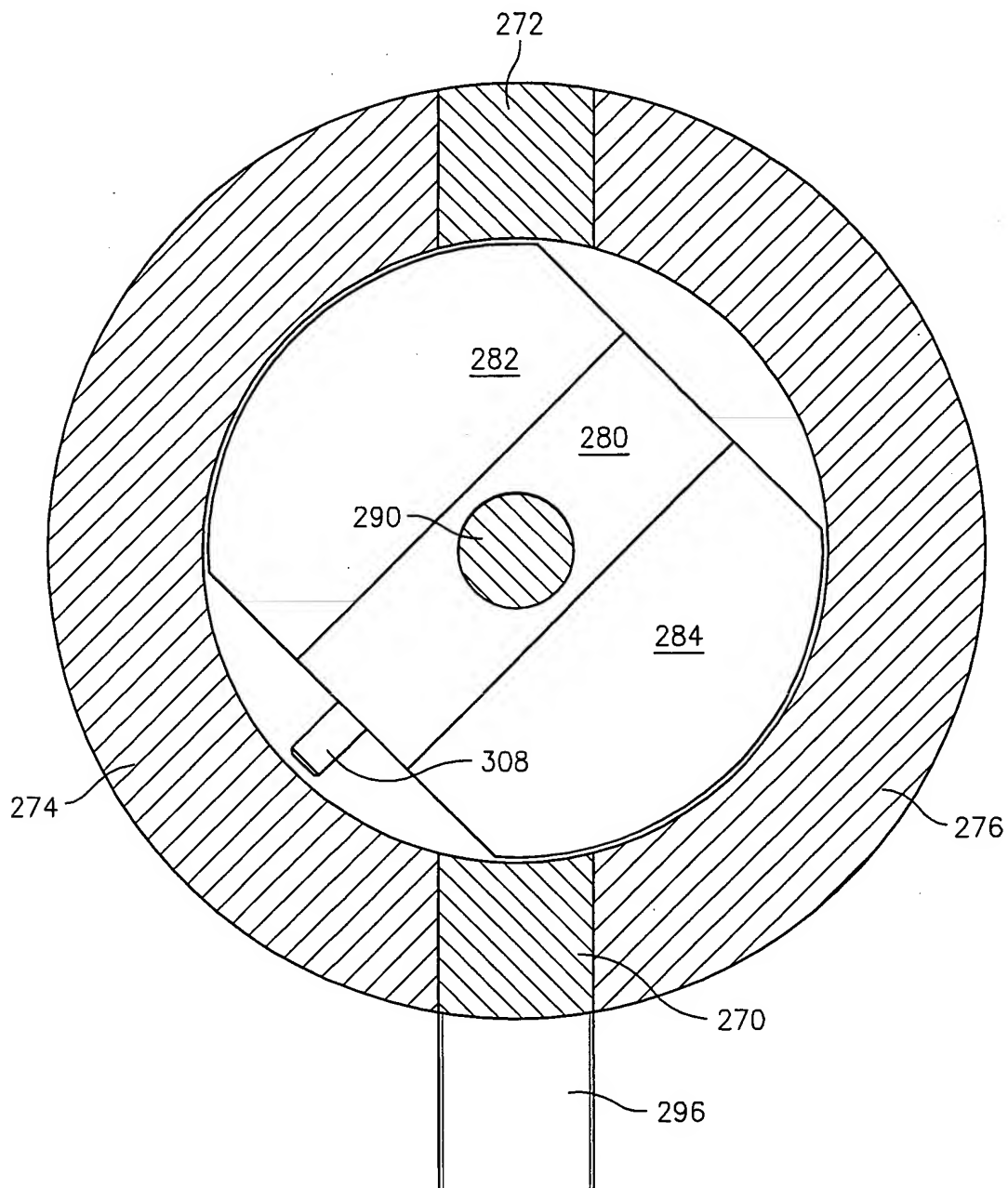


FIG. 34

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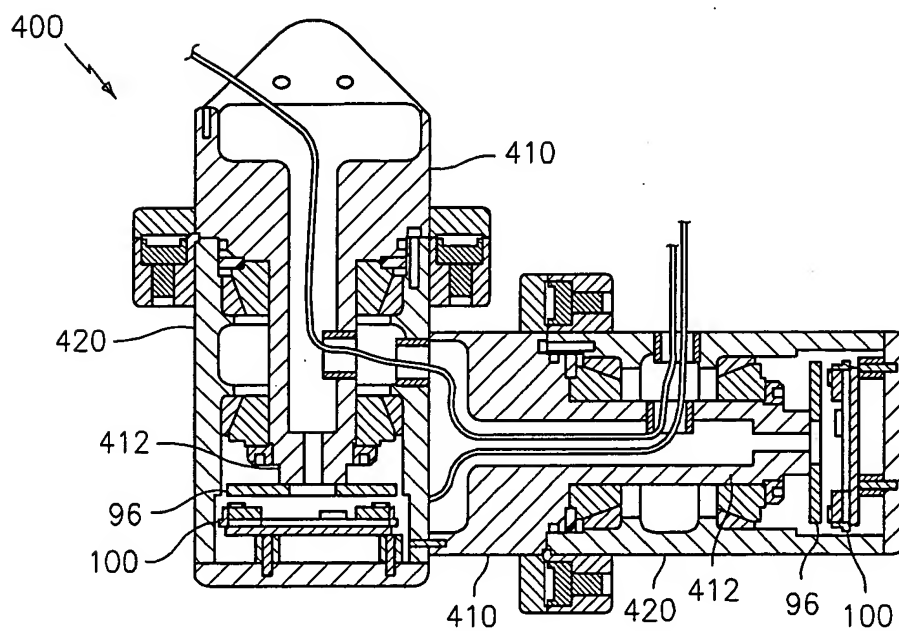


FIG. 35

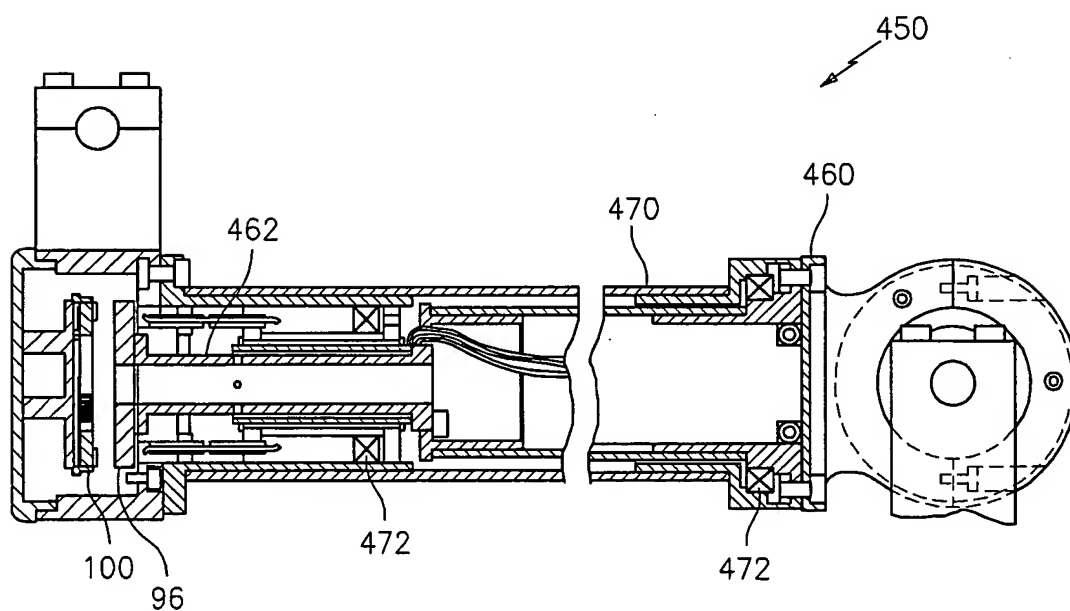


FIG. 36

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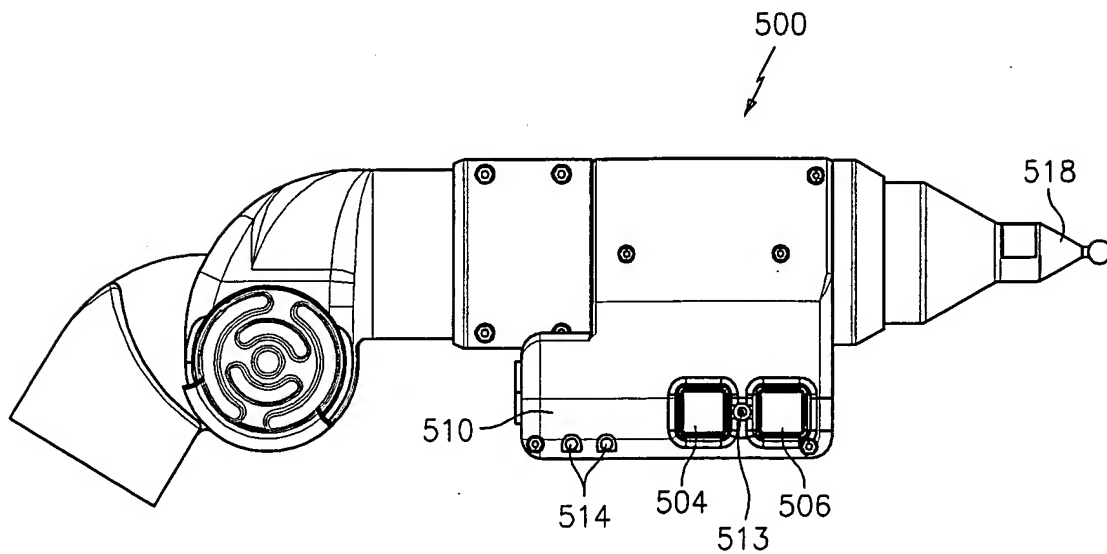


FIG. 37

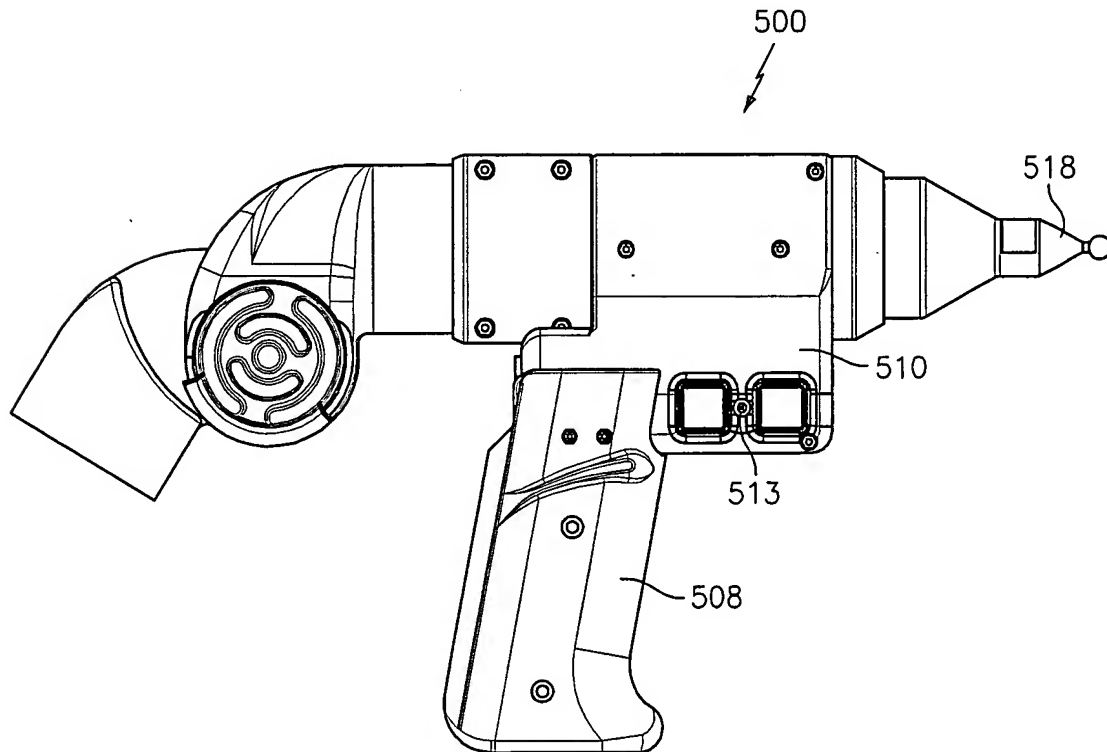


FIG. 38

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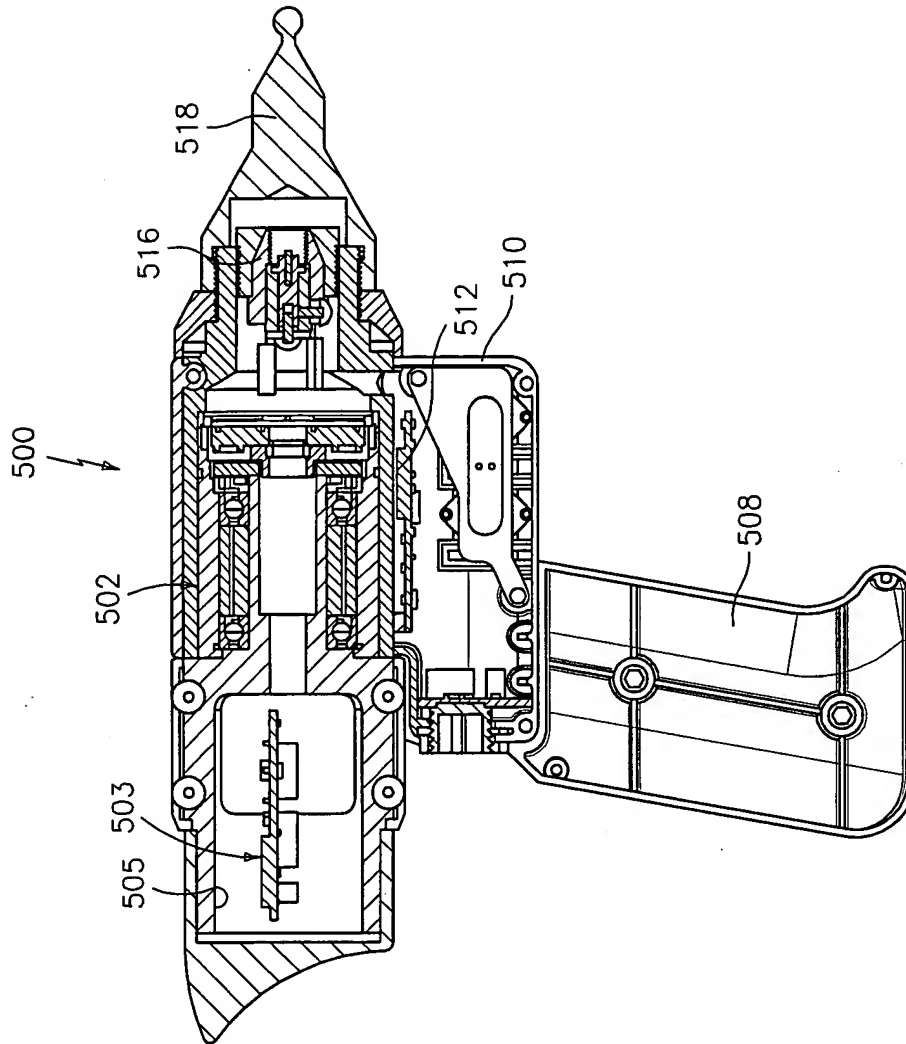


FIG. 40

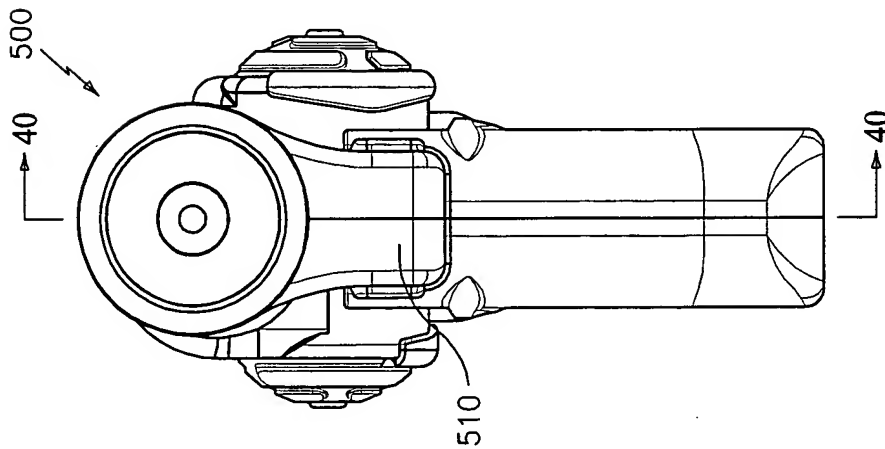
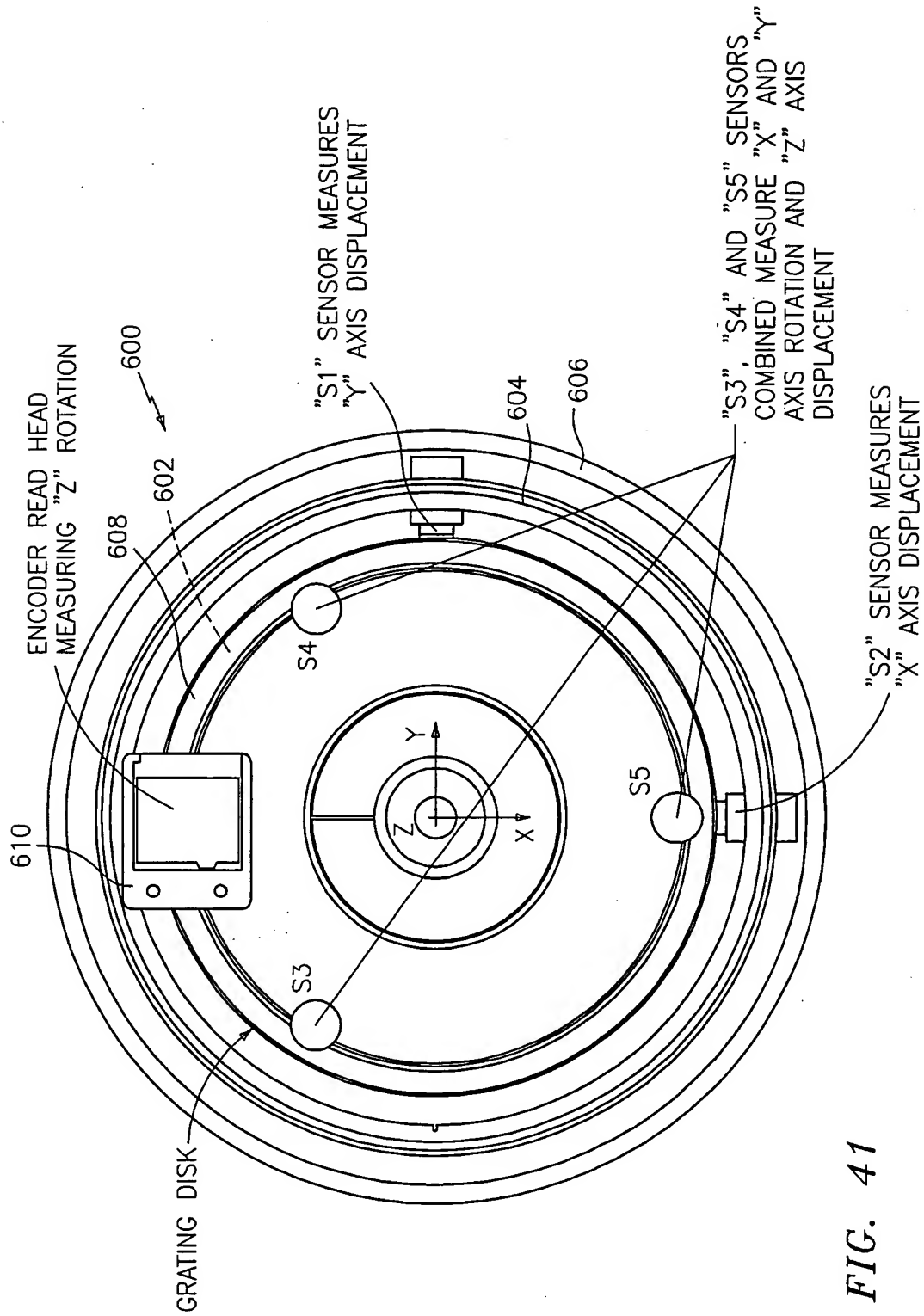


FIG. 39

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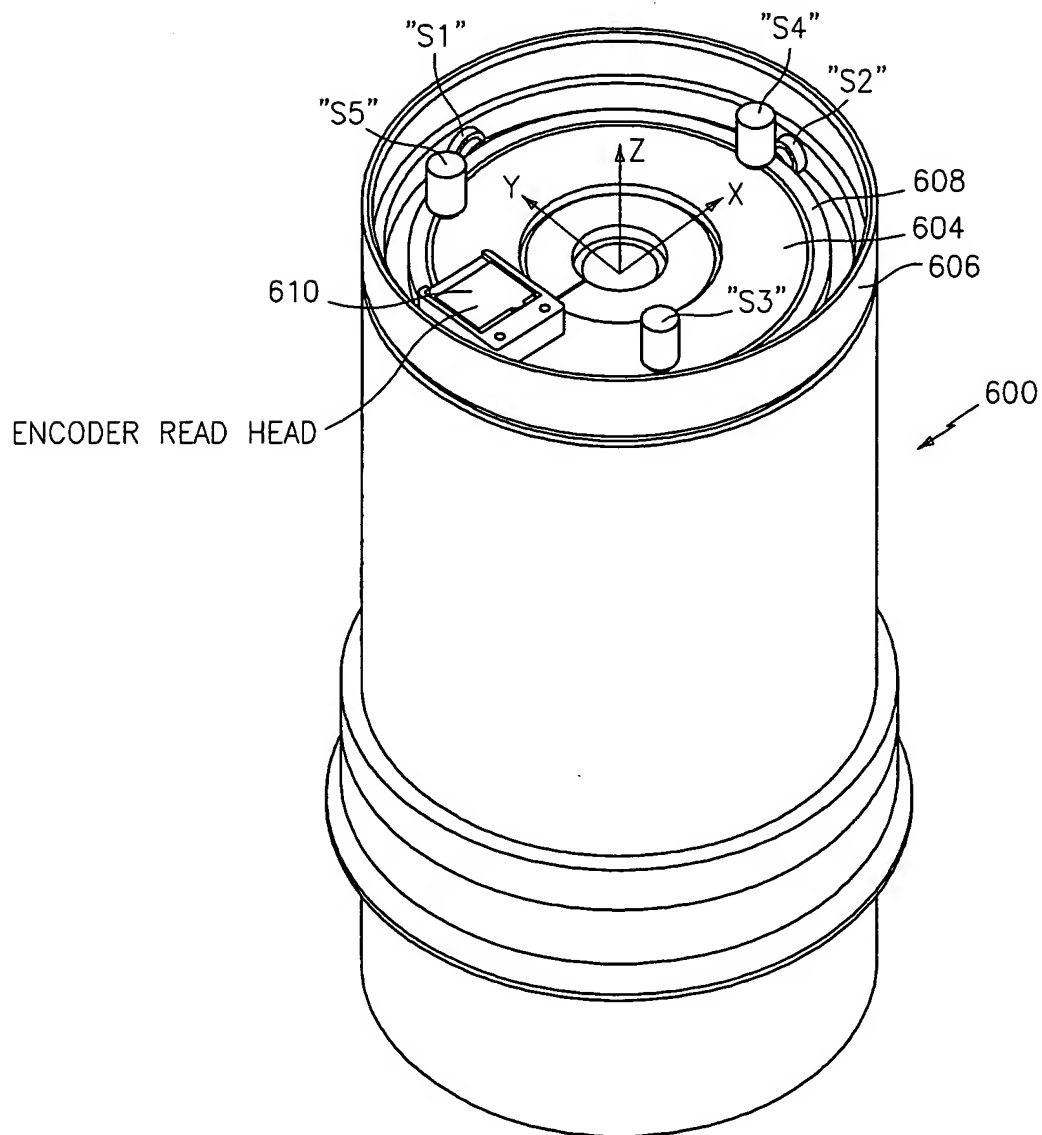


FIG. 42

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